

# A Deterministic Almost-Tight Distributed Algorithm for Approximating Single-Source Shortest Paths

Monika Henzinger<sup>1</sup>   Sebastian Krinninger<sup>2</sup>   Danupon Nanongkai<sup>3</sup>

<sup>1</sup>University of Vienna

<sup>2</sup>Max Planck Institute for Informatics

<sup>3</sup>KTH Royal Institute of Technology

STOC 2016

# Introduction

## The problem:

- Single-source shortest paths
- Undirected graphs
- Positive edge weights  $\in \{1, \dots, \text{poly}(n)\}$
- Goal:  $(1 + \epsilon)$ - or  $(1 + o(1))$ -approximation ( $\epsilon = 1/\text{polylog}n$ )

# Introduction

## The problem:

- Single-source shortest paths
- Undirected graphs
- Positive edge weights  $\in \{1, \dots, \text{poly}(n)\}$
- Goal:  $(1 + \epsilon)$ - or  $(1 + o(1))$ -approximation ( $\epsilon = 1/\text{polylog}n$ )

## Distributed setting:

- Network modeled as undirected graph
- Processors can communicate with neighbors
- **CONGEST** model: synchronous rounds, message size  $O(\log n)$
- Running time = number of rounds
- Goal: every node knows distance to source

# Overview

## Upper bounds:

exact

$O(n)$

det.

[Bellman-Ford]

# Overview

## Upper bounds:

exact

$O(n)$

$O(\epsilon^{-1} \log \epsilon^{-1})$

$O(n^{1/2+\epsilon} + \text{Diam})$

det.

[Bellman-Ford]

rand.

[Lenzen, Patt-Shamir '13]

# Overview

## Upper bounds:

exact

$O(n)$

det.

[Bellman-Ford]

$O(\epsilon^{-1} \log \epsilon^{-1})$

$O(n^{1/2+\epsilon} + \text{Diam})$

rand.

[Lenzen, Patt-Shamir '13]

$1 + \epsilon$

$O(n^{1/2} \text{Diam}^{1/4} + \text{Diam})$

rand.

[Nanongkai '14]

# Overview

## Upper bounds:

exact	$O(n)$	det.	[Bellman-Ford]
$O(\epsilon^{-1} \log \epsilon^{-1})$	$O(n^{1/2+\epsilon} + \text{Diam})$	rand.	[Lenzen, Patt-Shamir '13]
$1 + \epsilon$	$O(n^{1/2} \text{Diam}^{1/4} + \text{Diam})$	rand.	[Nanongkai '14]
$1 + o(1)$	$O(n^{1/2+o(1)} + \text{Diam}^{1+o(1)})$	det.	<b>[Our result]</b>

# Overview

## Upper bounds:

exact	$O(n)$	det.	[Bellman-Ford]
$O(\epsilon^{-1} \log \epsilon^{-1})$	$O(n^{1/2+\epsilon} + \text{Diam})$	rand.	[Lenzen, Patt-Shamir '13]
$1 + \epsilon$	$O(n^{1/2} \text{Diam}^{1/4} + \text{Diam})$	rand.	[Nanongkai '14]
$1 + o(1)$	$O(n^{1/2+o(1)} + \text{Diam}^{1+o(1)})$	det.	[Our result]

**Lower bound:**  $\Omega(n^{1/2} / \log n + \text{Diam})$  for any reasonable approximation  
[Das Sarma et al. '11]

# Overview

## Upper bounds:

exact	$O(n)$	det.	[Bellman-Ford]
$O(\epsilon^{-1} \log \epsilon^{-1})$	$O(n^{1/2+\epsilon} + \text{Diam})$	rand.	[Lenzen, Patt-Shamir '13]
$1 + \epsilon$	$O(n^{1/2} \text{Diam}^{1/4} + \text{Diam})$	rand.	[Nanongkai '14]
$1 + o(1)$	$O(n^{1/2+o(1)} + \text{Diam}^{1+o(1)})$	det.	[Our result]

**Lower bound:**  $\Omega(n^{1/2} / \log n + \text{Diam})$  for any reasonable approximation  
[Das Sarma et al. '11]

## Our approach:

- 1 Compute overlay network
- 2 Compute hop set and approximate SSSP on overlay network

# Overview

## Upper bounds:

exact	$O(n)$	det.	[Bellman-Ford]
$O(\epsilon^{-1} \log \epsilon^{-1})$	$O(n^{1/2+\epsilon} + \text{Diam})$	rand.	[Lenzen, Patt-Shamir '13]
$1 + \epsilon$	$O(n^{1/2} \text{Diam}^{1/4} + \text{Diam})$	rand.	[Nanongkai '14]
$1 + o(1)$	$O(n^{1/2+o(1)} + \text{Diam}^{1+o(1)})$	det.	[Our result]

**Lower bound:**  $\Omega(n^{1/2} / \log n + \text{Diam})$  for any reasonable approximation  
[Das Sarma et al. '11]

## Our approach:

- 1 Compute overlay network  
Derandomization of “hitting paths” argument at cost of approximation
- 2 Compute hop set and approximate SSSP on overlay network  
Deterministic hop set using greedy hitting set heuristic

## Summary of Results

### Theorem (CONGEST)

*There is a deterministic distributed algorithm that, on any weighted undirected network, computes  $(1 + o(1))$ -approximate shortest paths between a given source node  $s$  and every other node in  $O(n^{1/2+o(1)} + D^{1+o(1)})$  rounds.*

## Summary of Results

### Theorem (CONGEST)

*There is a deterministic distributed algorithm that, on any weighted undirected network, computes  $(1 + o(1))$ -approximate shortest paths between a given source node  $s$  and every other node in  $O(n^{1/2+o(1)} + D^{1+o(1)})$  rounds.*

### Theorem (Congested Clique)

*There is a deterministic distributed algorithm that, on any weighted congested clique, computes  $(1 + o(1))$ -approximate shortest paths between a given source node  $s$  and every other node in  $O(n^{o(1)})$  rounds.*

## Summary of Results

### Theorem (CONGEST)

*There is a deterministic distributed algorithm that, on any weighted undirected network, computes  $(1 + o(1))$ -approximate shortest paths between a given source node  $s$  and every other node in  $O(n^{1/2+o(1)} + D^{1+o(1)})$  rounds.*

### Theorem (Congested Clique)

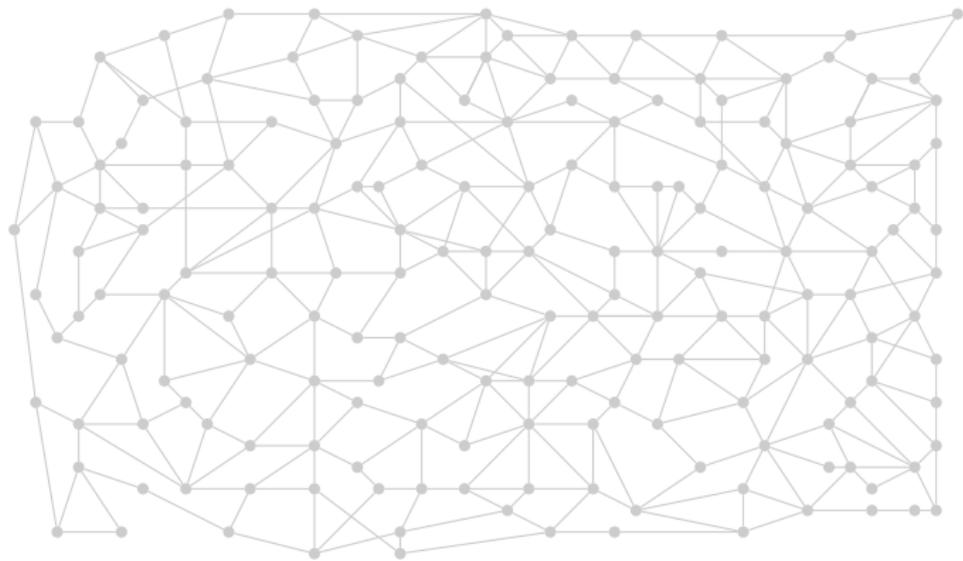
*There is a deterministic distributed algorithm that, on any weighted congested clique, computes  $(1 + o(1))$ -approximate shortest paths between a given source node  $s$  and every other node in  $O(n^{o(1)})$  rounds.*

### Theorem (Streaming)

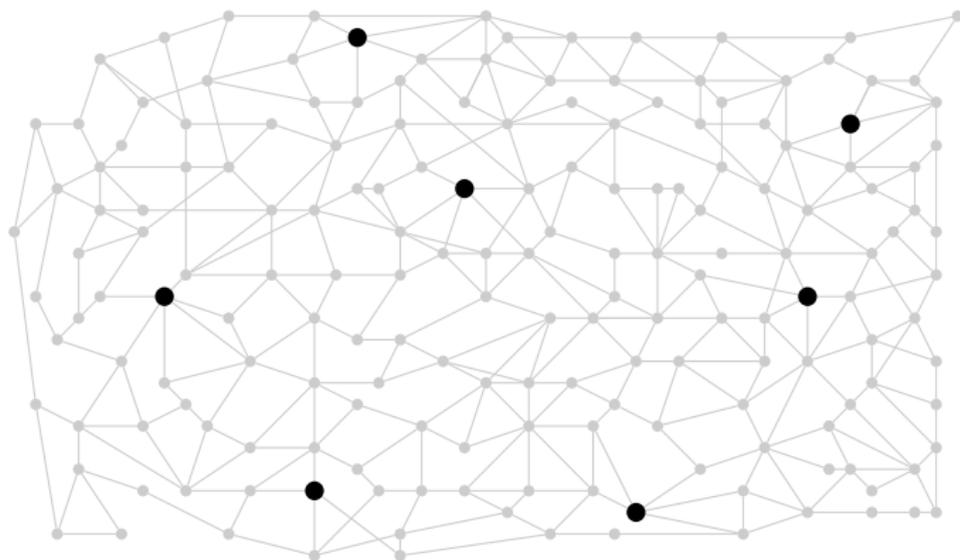
*There is a deterministic streaming algorithm that, given any weighted undirected graph, computes  $(1 + o(1))$ -approximate shortest paths between a given source node  $s$  and every other node in  $O(n^{o(1)} \log W)$  passes with  $O(n^{1+o(1)} \log W)$  space.*

# Computing Overlay Network

# Overlay Network

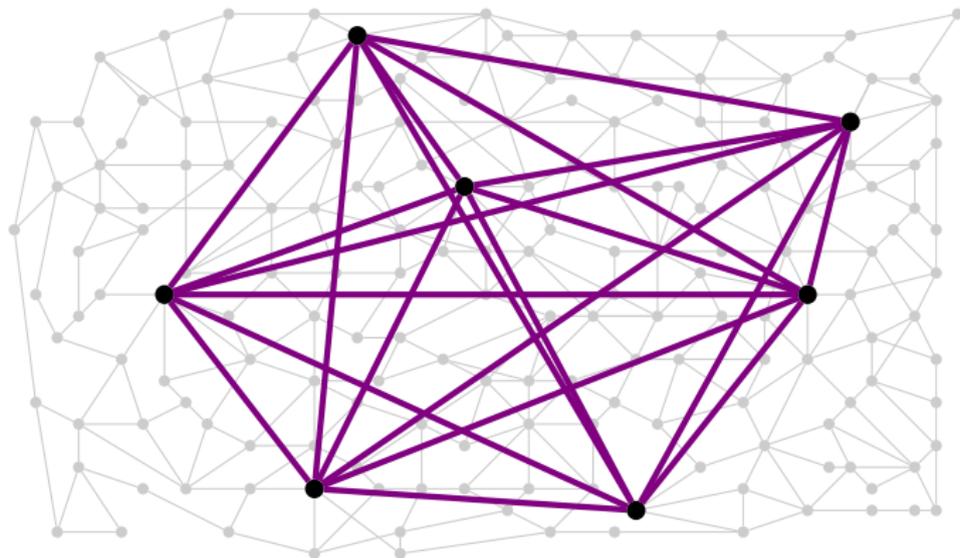


# Overlay Network



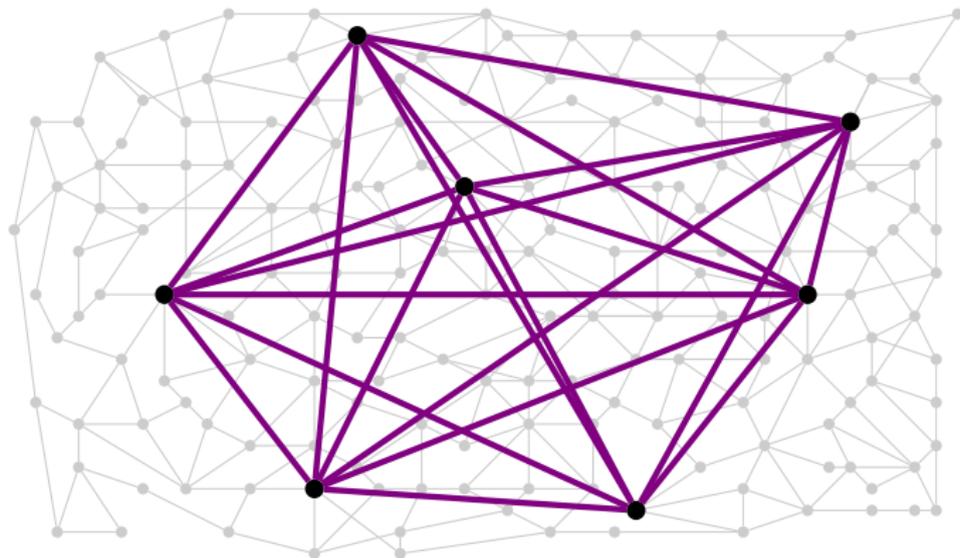
- 1 Sample  $N = O(\sqrt{n} \log n)$  centers (+ source  $s$ )  
 $\Rightarrow$  Every shortest path with  $\geq \sqrt{n}$  edges contains center whp

# Overlay Network



- 1 Sample  $N = O(\sqrt{n} \log n)$  centers (+ source  $s$ )  
 $\Rightarrow$  Every shortest path with  $\geq \sqrt{n}$  edges contains center whp
- 2 For every node: compute approx. shortest paths to centers within  $\sqrt{n}$  edges in  $O(\sqrt{n}\epsilon^{-1})$  rounds (**source detection** [Lenzen/Peleg '13])

# Overlay Network



- 1 Sample  $N = O(\sqrt{n} \log n)$  centers (+ source  $s$ )  
 $\Rightarrow$  Every shortest path with  $\geq \sqrt{n}$  edges contains center whp
- 2 For every node: compute approx. shortest paths to centers within  $\sqrt{n}$  edges in  $O(\sqrt{n}\epsilon^{-1})$  rounds (**source detection** [Lenzen/Peleg '13])
- 3 Sufficient to solve SSSP on overlay network using hop set

# Derandomization

## Property from randomization

$O(\sqrt{n} \log n)$  centers that hit every shortest path with  $\geq \sqrt{n}$  edges



# Derandomization

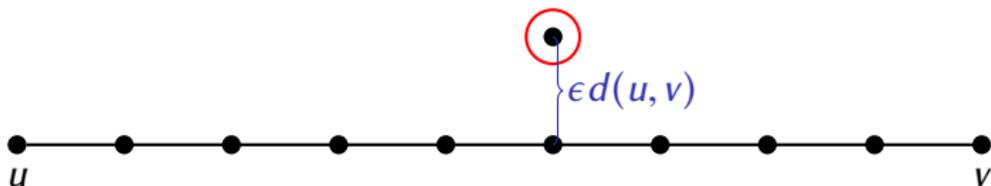
## Property from randomization

$O(\sqrt{n} \log n)$  centers that hit every shortest path with  $\geq \sqrt{n}$  edges



## Deterministic relaxation

$O(\sqrt{n}\epsilon^{-1} \log n)$  centers that **almost** hit every path with  $\geq \sqrt{n}$  edges



## Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

## Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

### Definition

$(\alpha, \beta)$ -**ruling set**  $R$  of  $U$  is a set of **rulers** such that

- Every pair of rulers in  $R$  is at distance  $\geq \alpha$  from each other
- Every node in  $U$  has a ruler in  $R$  at distance  $\leq \beta$

# Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

## Definition

$(\alpha, \beta)$ -**ruling set**  $R$  of  $U$  is a set of **rulers** such that

- Every pair of rulers in  $R$  is at distance  $\geq \alpha$  from each other
- Every node in  $U$  has a ruler in  $R$  at distance  $\leq \beta$

## Lemma ([Goldberg et al. '88])

*A  $(c, c \log n)$ -ruling set can be computed in  $O(c \log n)$  rounds.*

## Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

### Definition

$(\alpha, \beta)$ -**ruling set**  $R$  of  $U$  is a set of **rulers** such that

- Every pair of rulers in  $R$  is at distance  $\geq \alpha$  from each other
- Every node in  $U$  has a ruler in  $R$  at distance  $\leq \beta$

### Lemma ([Goldberg et al. '88])

*A  $(c, c \log n)$ -ruling set can be computed in  $O(c \log n)$  rounds.*

### Our setting:

- $U =$  all nodes  $v$  with  $|Ball(v, \sqrt{n})| \geq \sqrt{n}$
- $c = \epsilon \sqrt{n}$

## Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

### Definition

$(\alpha, \beta)$ -**ruling set**  $R$  of  $U$  is a set of **rulers** such that

- Every pair of rulers in  $R$  is at distance  $\geq \alpha$  from each other
- Every node in  $U$  has a ruler in  $R$  at distance  $\leq \beta$

### Lemma ([Goldberg et al. '88])

A  $(c, c \log n)$ -ruling set can be computed in  $O(c \log n)$  rounds.

### Our setting:

- $U =$  all nodes  $v$  with  $|Ball(v, \sqrt{n})| \geq \sqrt{n}$
- $c = \epsilon \sqrt{n}$
- Any shortest  $u - v$  path with  $\geq \sqrt{n}$  edges: ruler in distance  $\leq \epsilon \text{dist}(u, v)$

## Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

### Definition

$(\alpha, \beta)$ -**ruling set**  $R$  of  $U$  is a set of **rulers** such that

- Every pair of rulers in  $R$  is at distance  $\geq \alpha$  from each other
- Every node in  $U$  has a ruler in  $R$  at distance  $\leq \beta$

### Lemma ([Goldberg et al. '88])

A  $(c, c \log n)$ -ruling set can be computed in  $O(c \log n)$  rounds.

### Our setting:

- $U =$  all nodes  $v$  with  $|Ball(v, \sqrt{n})| \geq \sqrt{n}$
- $c = \epsilon \sqrt{n}$
- Any shortest  $u - v$  path with  $\geq \sqrt{n}$  edges: ruler in distance  $\leq \epsilon \text{dist}(u, v)$
- Uniquely assign  $\epsilon \sqrt{n}/2$  nodes to every ruler  $\Rightarrow |T| \leq 2 \sqrt{n}/\epsilon$

# Ruling sets for deterministic centers

**First:** Explanation for unweighted graphs

## Definition

$(\alpha, \beta)$ -**ruling set**  $R$  of  $U$  is a set of **rulers** such that

- Every pair of rulers in  $R$  is at distance  $\geq \alpha$  from each other
- Every node in  $U$  has a ruler in  $R$  at distance  $\leq \beta$

## Lemma ([Goldberg et al. '88])

A  $(c, c \log n)$ -ruling set can be computed in  $O(c \log n)$  rounds.

## Our setting:

- $U =$  all nodes  $v$  with  $|Ball(v, \sqrt{n})| \geq \sqrt{n}$
- $c = \epsilon \sqrt{n}$
- Any shortest  $u - v$  path with  $\geq \sqrt{n}$  edges: ruler in distance  $\leq \epsilon \text{dist}(u, v)$
- Uniquely assign  $\epsilon \sqrt{n}/2$  nodes to every ruler  $\Rightarrow |T| \leq 2 \sqrt{n}/\epsilon$

**Crucial:** “weight = #edges” in unweighted graphs

## Weighted graphs

**Goal:** Make graph locally “look unweighted” s.t.  $\text{weight} \approx \# \text{hops}$

# Weighted graphs

**Goal:** Make graph locally “look unweighted” s.t.  $\text{weight} \approx \text{\#hops}$

Well-known weight rounding [Bernstein '09/13, Madry '10, ...]

$G_i$ : round up edge weights to next multiple of  $\epsilon 2^i / \sqrt{n}$  ( $\forall i = 1$  to  $\log(nW)$ )  
 $(1 + \epsilon)$ -approximation of shortest paths with  $\sqrt{n}$  edges and weight  $2^i \dots 2^{i+1}$

**Intuition:** “weight  $\leq$  #edges”

# Weighted graphs

**Goal:** Make graph locally “look unweighted” s.t.  $\text{weight} \approx \text{\#hops}$

Well-known weight rounding [Bernstein '09/13, Madry '10, ...]

$G_i$ : round up edge weights to next multiple of  $\epsilon 2^i / \sqrt{n}$  ( $\forall i = 1$  to  $\log(nW)$ )  
 $(1 + \epsilon)$ -approximation of shortest paths with  $\sqrt{n}$  edges and weight  $2^i \dots 2^{i+1}$

**Intuition:** “weight  $\leq$  #edges”

Not enough: we also want “#edges  $\leq$  weight”

# Weighted graphs

**Goal:** Make graph locally “look unweighted” s.t.  $\text{weight} \approx \text{\#hops}$

Well-known weight rounding [Bernstein '09/13, Madry '10, ...]

$G_i$ : round up edge weights to next multiple of  $\epsilon 2^i / \sqrt{n}$  ( $\forall i = 1$  to  $\log(nW)$ )  
( $1 + \epsilon$ )-approximation of shortest paths with  $\sqrt{n}$  edges and weight  $2^i \dots 2^{i+1}$

**Intuition:** “weight  $\leq$  #edges”

Not enough: we also want “#edges  $\leq$  weight”

**Type**  $t(v)$  of node  $v$ : minimum  $i$  such that  $|Ball_{G_i}(v, (2 + \epsilon) \sqrt{n})| \geq \epsilon \sqrt{n}$

Intuition: type gives scale s.t. local neighborhood “looks unweighted”

# Weighted graphs

**Goal:** Make graph locally “look unweighted” s.t.  $\text{weight} \approx \text{\#hops}$

Well-known weight rounding [Bernstein '09/13, Madry '10, ...]

$G_i$ : round up edge weights to next multiple of  $\epsilon 2^i / \sqrt{n}$  ( $\forall i = 1$  to  $\log(nW)$ )  
 $(1 + \epsilon)$ -approximation of shortest paths with  $\sqrt{n}$  edges and weight  $2^i \dots 2^{i+1}$

**Intuition:** “weight  $\leq$  #edges”

Not enough: we also want “#edges  $\leq$  weight”

**Type**  $t(v)$  of node  $v$ : minimum  $i$  such that  $|Ball_{G_i}(v, (2 + \epsilon) \sqrt{n})| \geq \epsilon \sqrt{n}$

Intuition: type gives scale s.t. local neighborhood “looks unweighted”

**Lemma**

Every path  $\pi$  with  $\sqrt{n}$  edges contains a node  $v$  such that  $2^{t(v)} \leq 2\epsilon w(\pi)$ .

# Weighted graphs

**Goal:** Make graph locally “look unweighted” s.t.  $\text{weight} \approx \text{\#hops}$

Well-known weight rounding [Bernstein '09/13, Madry '10, ...]

$G_i$ : round up edge weights to next multiple of  $\epsilon 2^i / \sqrt{n}$  ( $\forall i = 1$  to  $\log(nW)$ )  
 $(1 + \epsilon)$ -approximation of shortest paths with  $\sqrt{n}$  edges and weight  $2^i \dots 2^{i+1}$

**Intuition:** “weight  $\leq$  #edges”

Not enough: we also want “#edges  $\leq$  weight”

**Type**  $t(v)$  of node  $v$ : minimum  $i$  such that  $|\text{Ball}_{G_i}(v, (2 + \epsilon) \sqrt{n})| \geq \epsilon \sqrt{n}$

Intuition: type gives scale s.t. local neighborhood “looks unweighted”

**Lemma**

Every path  $\pi$  with  $\sqrt{n}$  edges contains a node  $v$  such that  $2^{t(v)} \leq 2\epsilon w(\pi)$ .

$\Rightarrow$  Determine centers by computing ruling set for all type classes

# Computing Hop Set on Overlay Network

# Hop Sets

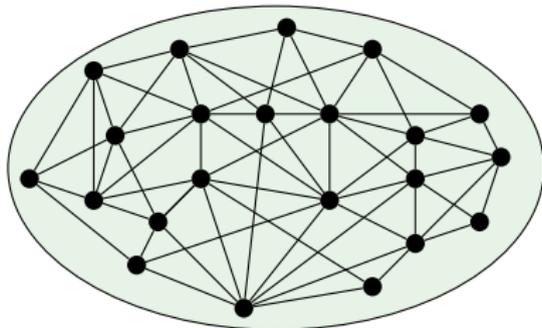
## Definition

An  $(h, \epsilon)$ -hop set is a set of weighted edges  $F$  such that, for all pairs of nodes  $u$  and  $v$ , in the 'shortcut graph'  $G \cup F$  there is a path from  $u$  to  $v$  with **at most  $h$  edges** of weight at most  $(1 + \epsilon)dist(u, v)$ .

# Hop Sets

## Definition

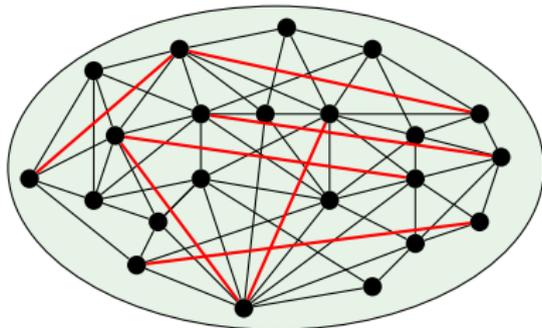
An  $(h, \epsilon)$ -hop set is a set of weighted edges  $F$  such that, for all pairs of nodes  $u$  and  $v$ , in the 'shortcut graph'  $G \cup F$  there is a path from  $u$  to  $v$  with **at most  $h$  edges** of weight at most  $(1 + \epsilon)dist(u, v)$ .



# Hop Sets

## Definition

An  $(h, \epsilon)$ -hop set is a set of weighted edges  $F$  such that, for all pairs of nodes  $u$  and  $v$ , in the 'shortcut graph'  $G \cup F$  there is a path from  $u$  to  $v$  with at most  $h$  edges of weight at most  $(1 + \epsilon) \text{dist}(u, v)$ .

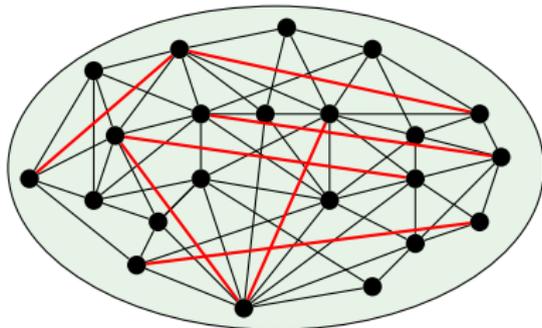


**Application:** SSSP up to small #edges can be done fast in overlay network

# Hop Sets

## Definition

An  $(h, \epsilon)$ -hop set is a set of weighted edges  $F$  such that, for all pairs of nodes  $u$  and  $v$ , in the 'shortcut graph'  $G \cup F$  there is a path from  $u$  to  $v$  with at most  $h$  edges of weight at most  $(1 + \epsilon) \text{dist}(u, v)$ .



**Application:** SSSP up to small #edges can be done fast in overlay network

A:  $(\log^{O(1)} n, \epsilon)$ -hop set of size  $n^{1+o(1)}$  [Cohen '94]

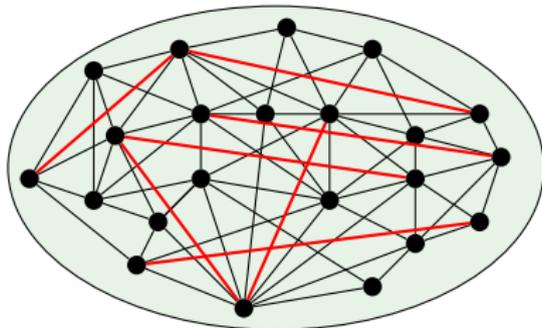
B:  $(n^{o(1)}, \epsilon)$ -hop set of size  $n^{1+o(1)}$  [Bernstein '09]

C:  $(n^\alpha, \epsilon)$ -hop set of size  $O(n)$  [Miller et al. '15]

# Hop Sets

## Definition

An  $(h, \epsilon)$ -hop set is a set of weighted edges  $F$  such that, for all pairs of nodes  $u$  and  $v$ , in the 'shortcut graph'  $G \cup F$  there is a path from  $u$  to  $v$  with at most  $h$  edges of weight at most  $(1 + \epsilon) \text{dist}(u, v)$ .



**Application:** SSSP up to small #edges can be done fast in overlay network

**A:**  $(\log^{O(1)} n, \epsilon)$ -hop set of size  $n^{1+o(1)}$  [Cohen '94]

**B:**  $(n^{o(1)}, \epsilon)$ -hop set of size  $n^{1+o(1)}$  [Bernstein '09]

**C:**  $(n^\alpha, \epsilon)$ -hop set of size  $O(n)$  [Miller et al. '15]

**Our contribution:** Fast computation of **B** on overlay network

## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$

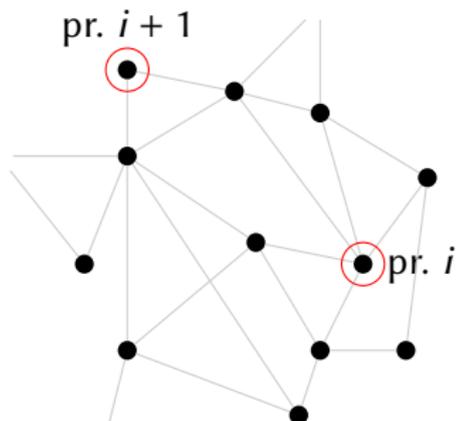
## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$



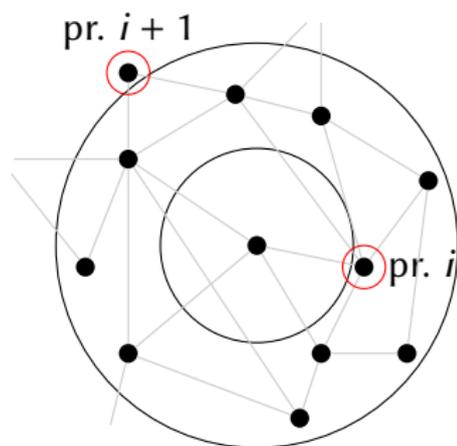
## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$



## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

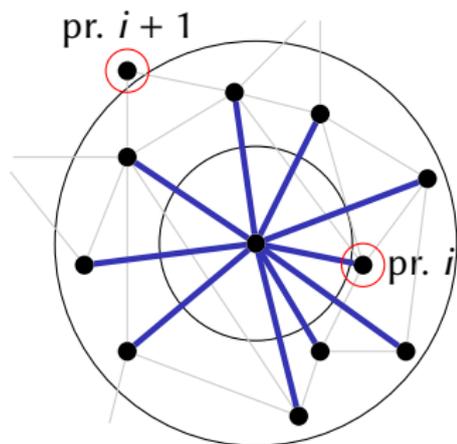
$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$

**Hop set:**

- $(u, v) \in F$  iff  $u \in Cluster(v)$
- $w(u, v) = dist_G(u, v)$



## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

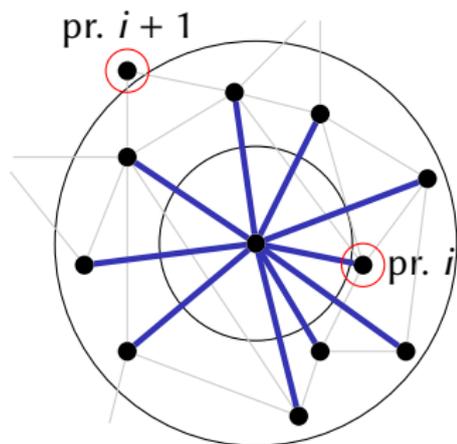
$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$

### Hop set:

- $(u, v) \in F$  iff  $u \in Cluster(v)$
- $w(u, v) = dist_G(u, v)$
- Guarantee:  $((4/\epsilon)^k, \epsilon)$ -hop set [Bernstein '09, Thorup/Zwick '06]
- Expected size:  $O(kn^{1+1/k})$  [Thorup/Zwick '01]



## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

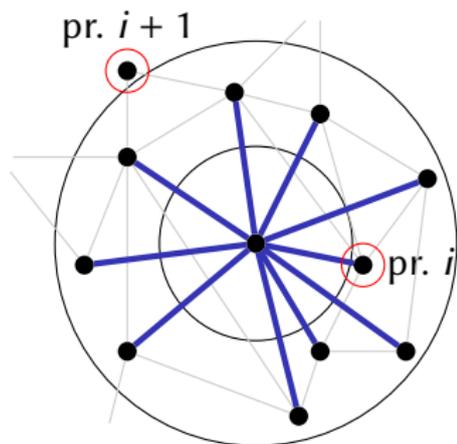
$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$

### Hop set:

- $(u, v) \in F$  iff  $u \in Cluster(v)$
- $w(u, v) = dist_G(u, v)$
- Guarantee:  $((4/\epsilon)^k, \epsilon)$ -hop set [Bernstein '09, Thorup/Zwick '06]
- Expected size:  $O(kn^{1+1/k})$  [Thorup/Zwick '01]
- With  $k = \sqrt{\log n / \log 4/\epsilon}$ :  $(n^{o(1)}, \epsilon)$ -hop set of size  $n^{1+o(1)}$



## Hop Set Based on Clusters [Thorup/Zwick '01]

$V = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = \emptyset$  where node of  $A_i$  goes to  $A_{i+1}$  with probability  $1/n^{1/k}$

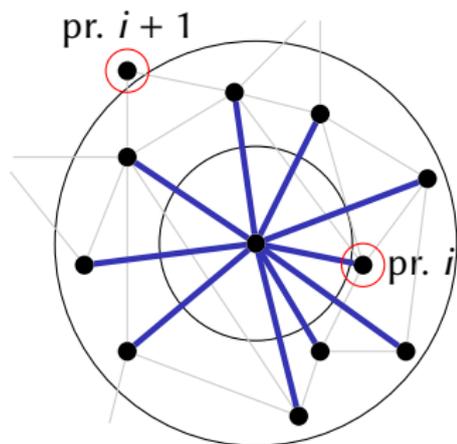
$v$  has **priority**  $i$  iff  $v \in A_i \setminus A_{i+1}$

For every node  $u$  of priority  $i$ :

$Cluster(v) = \{u \in V \mid dist(u, v) < dist(u, A_{i+1})\}$

### Hop set:

- $(u, v) \in F$  iff  $u \in Cluster(v)$
- $w(u, v) = dist_G(u, v)$
- Guarantee:  $((4/\epsilon)^k, \epsilon)$ -hop set [Bernstein '09, Thorup/Zwick '06]
- Expected size:  $O(kn^{1+1/k})$  [Thorup/Zwick '01]
- With  $k = \sqrt{\log n / \log 4/\epsilon}$ :  $(n^{o(1)}, \epsilon)$ -hop set of size  $n^{1+o(1)}$
- **Derandomization:** choose  $A_{i+1}$  from  $A_i$  by greedy hitting set heuristic  
(Sequential, but affordable in overlay network)



# Chicken-Egg Problem?

- ① Goal: Faster SSSP via hop set
  - ② Compute hop set by computing clusters
  - ③ Computing clusters at least as hard as SSSP
- ⇒ Back at problem we wanted to solve initially?



# Chicken-Egg Problem?

- 1 Goal: Faster SSSP via hop set
  - 2 Compute hop set by computing clusters
  - 3 Computing clusters at least as hard as SSSP
- ⇒ Back at problem we wanted to solve initially?



**No!** Iterative computation starting with

- SSSP up to small #hops is cheap in overlay network
- Clusters up to small #hops provide sufficient shortcutting to make progress in each iteration

# Computing $(n^{o(1)}, \epsilon)$ -hop set

## **Iterative computation**

In each iteration number of hops is reduced by a factor of  $n^{1/k}$

# Computing $(n^{o(1)}, \epsilon)$ -hop set

## Iterative computation

In each iteration number of hops is reduced by a factor of  $n^{1/k}$

### Algorithm:

**for**  $i = 1$  **to**  $k$  **do**

$$H_i = G \cup \bigcup_{1 \leq j \leq i-1} F_j$$

Compute clusters with  $k$  priorities in  $H_i$  up to  $n^{2/k}$  hops

$$F_i = \{(u, v) \mid u \in \text{Cluster}(v)\}$$

**end**

**return**  $F = \bigcup_{1 \leq i \leq k} F_i$

# Computing $(n^{o(1)}, \epsilon)$ -hop set

## Iterative computation

In each iteration number of hops is reduced by a factor of  $n^{1/k}$

### Algorithm:

**for**  $i = 1$  **to**  $k$  **do**

$$H_i = G \cup \bigcup_{1 \leq j \leq i-1} F_j$$

Compute clusters with  $k$  priorities in  $H_i$  up to  $n^{2/k}$  hops

$$F_i = \{(u, v) \mid u \in \text{Cluster}(v)\}$$

**end**

**return**  $F = \bigcup_{1 \leq i \leq k} F_i$

Error amplification:  $(1 + \epsilon')^k \leq (1 + \epsilon)$  for  $\epsilon' = 1/(2\epsilon \log n)$

# Computing $(n^{o(1)}, \epsilon)$ -hop set

## Iterative computation

In each iteration number of hops is reduced by a factor of  $n^{1/k}$

### Algorithm:

**for**  $i = 1$  **to**  $k$  **do**

$$H_i = G \cup \bigcup_{1 \leq j \leq i-1} F_j$$

Compute clusters with  $k$  priorities in  $H_i$  up to  $n^{2/k}$  hops

$$F_i = \{(u, v) \mid u \in \text{Cluster}(v)\}$$

**end**

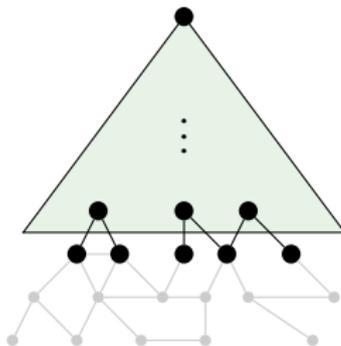
**return**  $F = \bigcup_{1 \leq i \leq k} F_i$

Error amplification:  $(1 + \epsilon')^k \leq (1 + \epsilon)$  for  $\epsilon' = 1/(2\epsilon \log n)$

**Omitted detail:** weighted graphs, use rounding technique

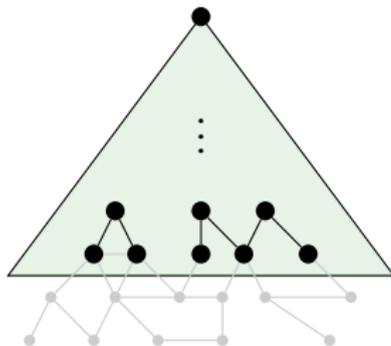
# Computing Hop Set on Overlay Network

Shortest paths from source  $s$  **up to distance**  $d$ :



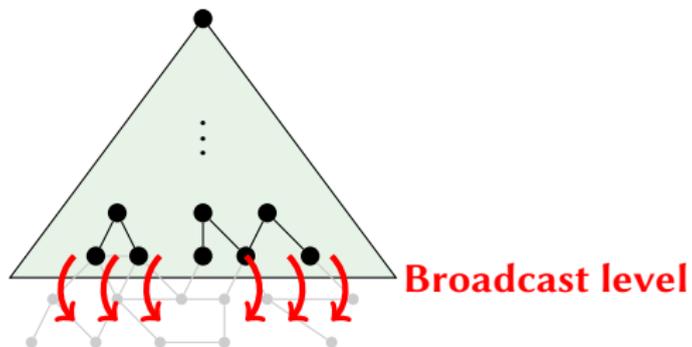
# Computing Hop Set on Overlay Network

Shortest paths from source  $s$  **up to distance**  $d$ :



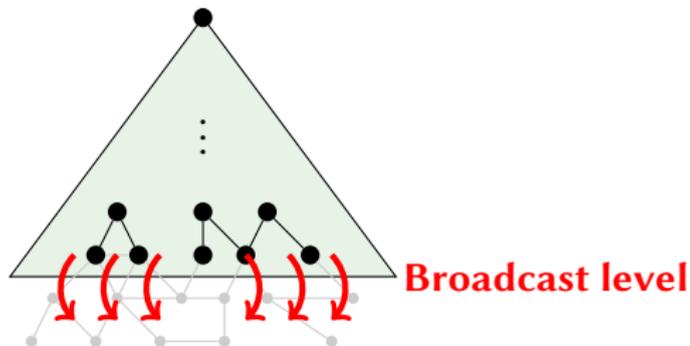
# Computing Hop Set on Overlay Network

Shortest paths from source  $s$  **up to distance**  $d$ :



# Computing Hop Set on Overlay Network

Shortest paths from source  $s$  **up to distance**  $d$ :

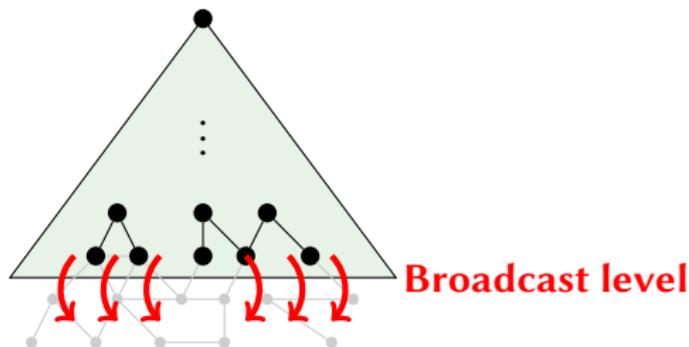


$d$  iterations, each  $O(Diam + N_\ell)$  rounds where  $N_\ell = \#nodes$  at level  $\ell$

Running time:  $O(d \cdot Diam + \sum_{l \leq d} N_\ell) = O(d \cdot Diam + N)$

# Computing Hop Set on Overlay Network

Shortest paths from source  $s$  **up to distance**  $d$ :



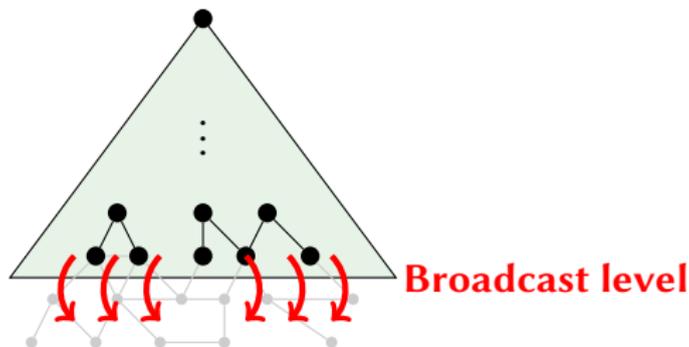
$d$  iterations, each  $O(Diam + N_\ell)$  rounds where  $N_\ell = \#nodes$  at level  $\ell$

Running time:  $O(d \cdot Diam + \sum_{l \leq d} N_\ell) = O(d \cdot Diam + N)$

Computing clusters:  $\tilde{O}(n^{1/k} \cdot Diam + \sum_v |Cluster(v)|) = \tilde{O}(n^{1/k} \cdot Diam + N^{1+1/k})$

# Computing Hop Set on Overlay Network

Shortest paths from source  $s$  **up to distance**  $d$ :



$d$  iterations, each  $O(Diam + N_\ell)$  rounds where  $N_\ell = \#nodes$  at level  $\ell$

Running time:  $O(d \cdot Diam + \sum_{l \leq d} N_\ell) = O(d \cdot Diam + N)$

Computing clusters:  $\tilde{O}(n^{1/k} \cdot Diam + \sum_v |Cluster(v)|) = \tilde{O}(n^{1/k} \cdot Diam + N^{1+1/k})$

$\Rightarrow$  Hop Set and approximate SSSP:  $O(n^{1/2+o(1)} + Diam^{1+o(1)})$  ( $N \approx \sqrt{n}$ )

# Conclusion

## **Main contributions:**

- Almost tight algorithm
- Deterministic overlay network and deterministic hop set

# Conclusion

## Main contributions:

- Almost tight algorithm
- Deterministic overlay network and deterministic hop set

## Open problems:

- $n^{o(1)} \rightarrow \log^{O(1)} n$   
Better hop set?
- Improve dependence on  $\epsilon$
- $O(n)$  rounds optimal for exact SSSP?

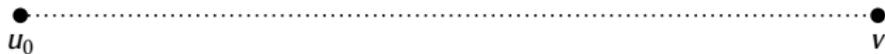
Example:  $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 1:  $\text{dist}(u_0, v) \leq n^{1/2+1/k}/\epsilon$



Example:  $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$



Example:  $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$

$$r_0 = n^{1/2}$$



## Example: $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$

$$r_0 = n^{1/2}$$



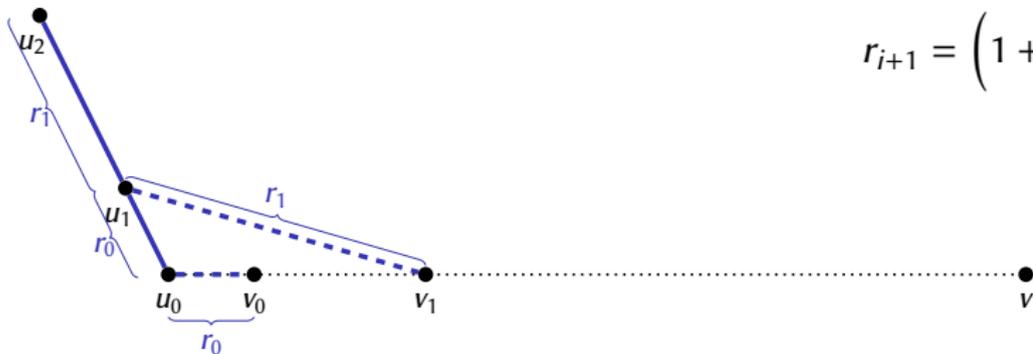
For every node  $u$  of priority  $i$  and every node  $v$ , either  $(u, v) \in H$ , or  $\exists u'$  of priority  $i + 1$  s. t.  $\text{dist}(u, u') \leq \text{dist}(u, v)$ .

## Example: $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$

$$r_0 = n^{1/2}$$

$$r_{i+1} = \left(1 + \frac{2}{\epsilon}\right) \sum_{0 \leq j \leq i} r_j$$



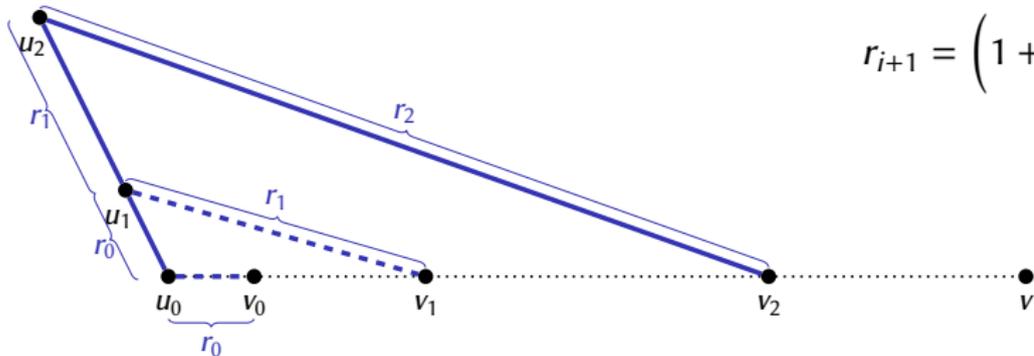
For every node  $u$  of priority  $i$  and every node  $v$ , either  $(u, v) \in H$ , or  $\exists u'$  of priority  $i + 1$  s. t.  $\text{dist}(u, u') \leq \text{dist}(u, v)$ .

# Example: $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$

$$r_0 = n^{1/2}$$

$$r_{i+1} = \left(1 + \frac{2}{\epsilon}\right) \sum_{0 \leq j \leq i} r_j$$



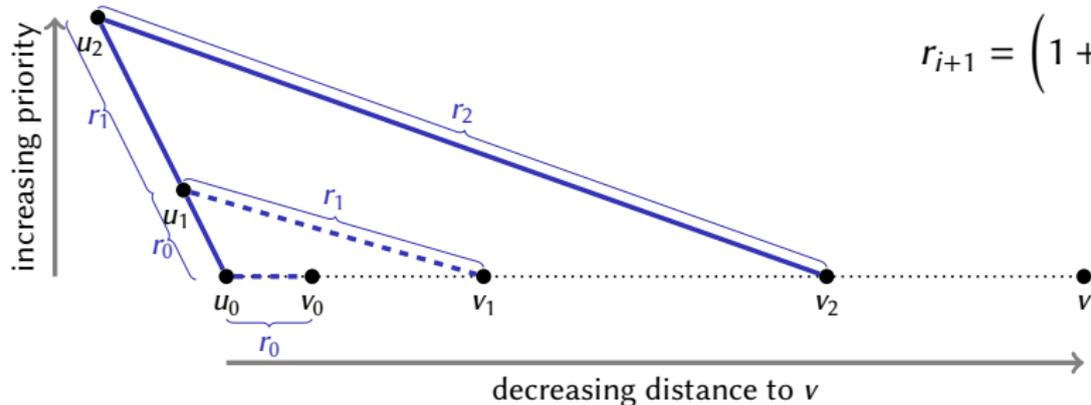
For every node  $u$  of priority  $i$  and every node  $v$ , either  $(u, v) \in H$ , or  $\exists u'$  of priority  $i + 1$  s. t.  $\text{dist}(u, u') \leq \text{dist}(u, v)$ .

# Example: $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$

$$r_0 = n^{1/2}$$

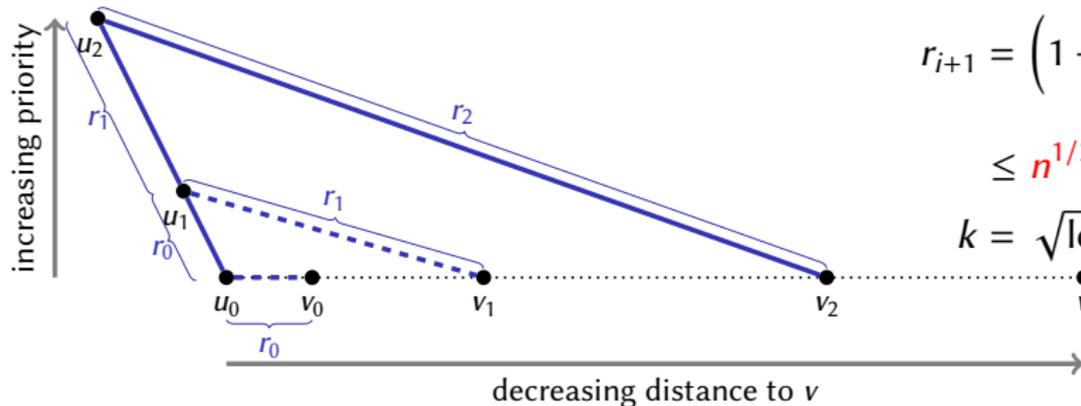
$$r_{i+1} = \left(1 + \frac{2}{\epsilon}\right) \sum_{0 \leq j \leq i} r_j$$



For every node  $u$  of priority  $i$  and every node  $v$ , either  $(u, v) \in H$ , or  $\exists u'$  of priority  $i + 1$  s. t.  $\text{dist}(u, u') \leq \text{dist}(u, v)$ .

## Example: $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$



$$r_0 = n^{1/2}$$

$$r_{i+1} = \left(1 + \frac{2}{\epsilon}\right) \sum_{0 \leq j \leq i} r_j$$

$$\leq n^{1/2} n^{1/k}$$

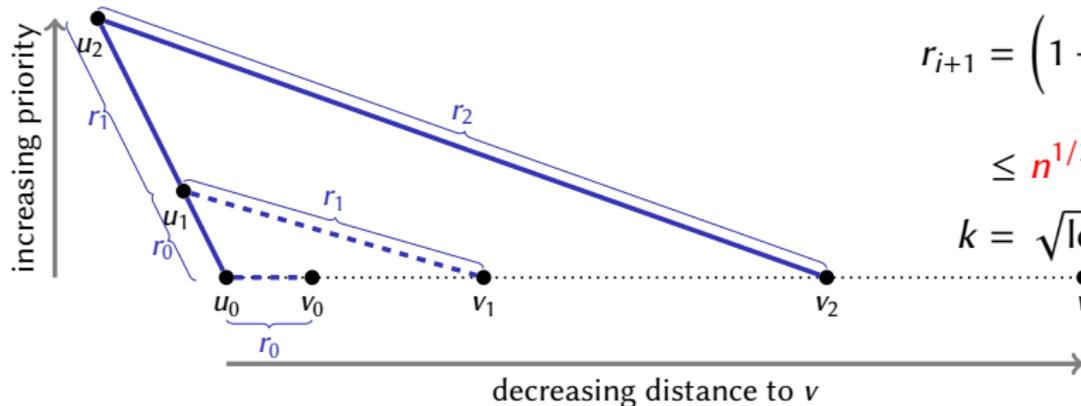
$$k = \sqrt{\log n} / \sqrt{\log 4/\epsilon}$$

For every node  $u$  of priority  $i$  and every node  $v$ , either  $(u, v) \in H$ , or  $\exists u'$  of priority  $i + 1$  s. t.  $\text{dist}(u, u') \leq \text{dist}(u, v)$ .

$$\text{Weight} \leq (1 + \epsilon) \text{dist}(u_0, v)$$

## Example: $(n^{1/2+o(1)}, \epsilon)$ -hop set

Case 2:  $\text{dist}(u_0, v) > n^{1/2+1/k}/\epsilon$



$$r_0 = n^{1/2}$$

$$r_{i+1} = \left(1 + \frac{2}{\epsilon}\right) \sum_{0 \leq j \leq i} r_j$$

$$\leq n^{1/2} n^{1/k}$$

$$k = \sqrt{\log n} / \sqrt{\log 4/\epsilon}$$

For every node  $u$  of priority  $i$  and every node  $v$ , either  $(u, v) \in H$ , or  $\exists u'$  of priority  $i + 1$  s. t.  $\text{dist}(u, u') \leq \text{dist}(u, v)$ .

$$\text{Weight} \leq (1 + \epsilon) \text{dist}(u_0, v)$$

$$\#Edges \leq \frac{k \cdot \text{dist}(u, v)}{n^{1/2}} \leq \frac{k \cdot n}{n^{1/2}} = kn^{1/2}$$