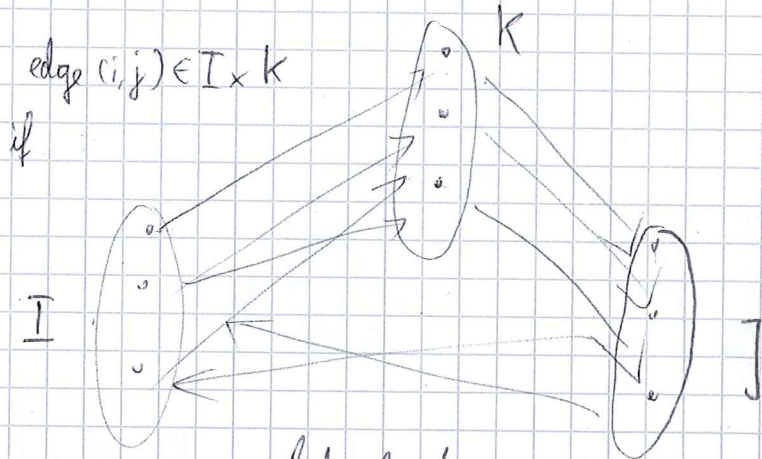


Min-Plus Product
From ~~2-Layer ARSP~~ to All-Pairs Negative Triangle

Construct sets of nodes I, K, J of size n each



weight of edges from J to I is adaptive

Goal: $\forall i, j$ compute $\min_k (w(i, k) + w(k, j))$
 = minimum integer z s.t. $w(i, k) + w(k, j) < z + 1$
there is a k with

Idea: ~~Find z by~~ For every i, j , we can test whether

$$\exists k: w(i, k) + w(k, j) < z(i, j) + 1$$

$$\Leftrightarrow \exists k: w(i, k) + w(k, j) + (-z(i, j) - 1) < 0$$

by setting $w(i, j) := -z(i, j) - 1$ and checking if there is a neg. triangle containing i and j

\rightarrow Find min. such $z(i, j)$ by simultaneous binary search

Weights are in $\{-n^c, \dots, n^c\}$

\rightarrow each entry of Min-Plus Product is in $\{-2n^c, \dots, 2n^c\}$

\rightarrow binary search takes $\log_2(4n^c + 1) = O(\log n)$ steps

$\Rightarrow T(n)$ -time alg. for All-Pairs Neg $\Delta \Rightarrow T(n) \log n$ -time for Min-Plus

Algorithm: $\forall i, j$ initialize $m(i, j) = -2n^c$ and $M(i, j) = 2n^c$

repeat $\log(4n^c)$ times:

$$\forall i, j: w(j, i) := -\lceil m(i, j) + M(i, j) / 2 \rceil$$

Compute All-Pairs Neg Triangle

$$\forall i, j: \text{if } i, j \text{ is in neg. triangle: } M(i, j) := -w(j, i) - 1$$

$$\text{otherwise: } m(i, j) = -w(j, i)$$

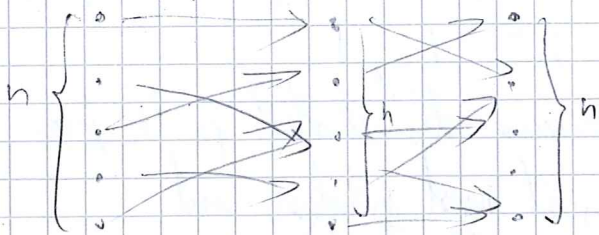
$$\forall i, j \text{ set } C_{ij} = M(i, j)$$

From APSP to min-Plus Product

$$C = \text{min-plus } A \otimes B$$

The reduction Min-Plus Product \rightarrow APSP ^{would be} is almost trivial:

Construct graph G :



$$w(i,k) = A[i,k] \quad w(k,j) = B[k,j]$$

Let u be i -th node on the left, let v be j -th node on the right

Then the shortest path from u to v has weight

$$\min_k (w(i,k) + w(k,j)) = \min_k (A[i,k] + B[k,j]) = C[i,j]$$

Theorem: Let A be the weighted adjacency matrix of a graph G with nodes $V = \{v_1, \dots, v_n\}$ and let B be the same as A with every diagonal entry set to 0, i.e. $B = A \oplus I$ in the min-plus semiring.

$$\begin{matrix} \uparrow & \uparrow \\ \text{min-plus min} & \end{matrix} \begin{pmatrix} 0 & \infty \\ \infty & 0 \end{pmatrix}$$

Then the matrix $C := (B^{\otimes \lceil \log n \rceil})$ (with exponentiation according to min-plus product) contains, for every i, j , entry $C[i,j] = \text{length of shortest path from } v_i \text{ to } v_j$.

Proof: We prove by induction on h : For all i, j

$$B^{\otimes h}[i,j] = \text{dist}^{\leq h}[i,j], \text{ i.e. length of shortest path from } v_i \text{ to } v_j \text{ with } \leq h \text{ edges}$$

Base case $h=0$: $B^{\otimes 0} = I$ \checkmark (every node is at distance 0 from itself)

$$\begin{aligned} \text{Inductive step: } h \rightarrow h+1: B^{\otimes h+1} &= B^{\otimes h} \otimes B = B^{\otimes h} \otimes (A \oplus I) \\ &= (B^{\otimes h} \otimes A) \oplus (B^{\otimes h} \otimes I) = (B^{\otimes h} \otimes A) \oplus B^{\otimes h} \end{aligned}$$

By IH: $B^{\otimes h}$ contains lengths of shortest paths with $\leq h$ edges

Every shortest path with $\leq h+1$ edges ^{either} consists ~~entirely~~ of $\leq h$ edges (" $B^{\otimes h}$ ")
or first a shortest path with $\leq h$ edges and then a single edge (" $B^{\otimes h} \otimes A$ ")
Thus $B^{\otimes h+1}$ is the desired matrix

The theorem now follows because

$$\begin{aligned} \text{Thus: } \text{dist}^{\leq h+1}(v_i, v_j) &= \min_k (\min(\text{dist}^h(v_i, v_k) + w(v_k, v_j), \\ &\quad \text{dist}^h(v_i, v_k))) \\ &= \min(B^h \otimes A[i, j], B^h[i, j]) \\ &= B^{h+1}[i, j] \end{aligned}$$

The theorem now follows because the shortest path from v_i to v_j (for all i, j) has at most $n-1$ edges and $n-1 \leq 2^{\lceil \log n \rceil}$ \square

How to compute $B^{2^{\lceil \log n \rceil}}$?

Repeated squaring: B

$$\begin{aligned} &\leq \log(2^{\lceil \log n \rceil + 1}) \\ &= O(\log n) \end{aligned}$$

many min-plus products

$$B^2 = B \otimes B$$

$$B^4 = B^2 \otimes B^2$$

\vdots

$$B^{2^{\lceil \log n \rceil}} = B^{2^{\lceil \log n \rceil - 1}} \otimes B^{2^{\lceil \log n \rceil - 1}}$$

Thm: If Min-Plus Product has a $T(n)$ -time algorithm, then APSP has an $O((T(n) + n^2) \log n)$ -time algorithm

Remark: The $\log n$ factor can be eliminated (see [Itzhak / Hopcroft / Ullman '74])

Remark: In the APSP problem, non-edges, i.e. pairs of nodes u, v s.t. $(u, v) \notin E$, can be simulated by

- adding an edge (u, v) of weight ∞ to the graph
- adding an edge (u, v) of weight nW to the graph (where W is the maximum weight in the input graph)

Reason for b): shortest path has length $\leq (n-1)W$

If shortest path after adding edges in step (b) has length $> (n-1)W$, we know that initially ~~no~~ no path existed

Subcubic Equivalence of Radius

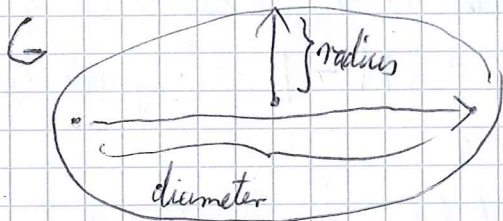
Definition (Radius):

Input: Weighted directed graph G with edge weights $\in \{0, 1, \dots, b\}$

Task: Output $\min_u \max_v \text{dist}(u, v)$ for some constant c

where $\text{dist}(u, v)$ = length of shortest path from u to v

Intuition: u is the ~~most~~ most central vertex



$\max_v \text{dist}(u, v)$ is also called eccentricity of u

We will prove:

Thm: APSP \equiv Radius (subcubic equivalent)

by showing

deg. Triangle \leq Radius and

Radius \leq APSP

Reduction: Radius \rightarrow APSP

- Compute all pairwise distances $T_{\text{APSP}}(n)$
- Evaluate definition of radius $O(n^2)$

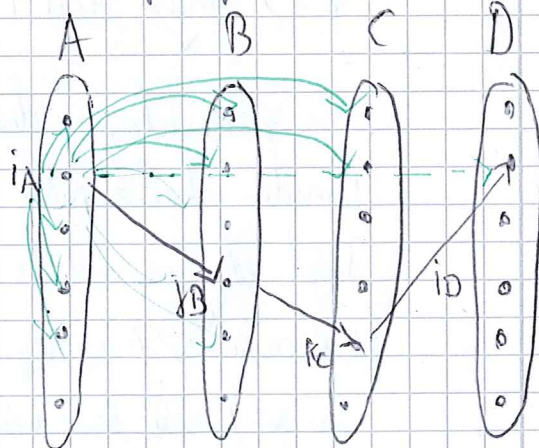
\rightarrow subcubic reduction with one oracle call

Reduction: Negative Triangle \rightarrow Radius

Given: directed graph with n nodes $\{1, \dots, n\}$ and edge weights in $\{-M, -M+1, \dots, M\}$ where $M = n^c$ for some constant c

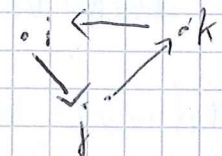
Construct directed graph H with $O(n)$ nodes and edge weights in $\{0, 1, \dots, O(M)\}$

- (1) Make 4 layers A, B, C, D with n nodes each $A = \{1_A, \dots, n_A\}$, etc.
- (2) For every edge (i, j) of G : add (i_A, j_B) , (j_B, i_C) , (i_C, j_D) of weight $M + w(i, j)$ to H
- (3) For every $1 \leq i \leq n$, add edges of weight $3M-1$ from i_A to all other nodes, except i_D and i_A



Lemma: ~~The radius of H is $\leq 3M-1$ iff~~
 G contains a negative triangle iff
the radius of H is $\leq 3M-1$

Proof:

" \Rightarrow " Consider triangle  of total weight $W \leq -1$

Then in H there is a path $i_A \rightarrow j_B \rightarrow k_C \rightarrow i_D$ of total weight $3M + W \leq 3M - 1$ (\uparrow by rule (2))

$$\Rightarrow \text{dist}(i_A, i_D) \leq 3M - 1$$

For any other vertex $v \neq i_D$: $\text{dist}(i_A, v) \leq 3M - 1$ by (3)

$$\Rightarrow \max_v \text{dist}(i_A, v) \leq 3M - 1$$

$$\Rightarrow \min_u \max_v \text{dist}(u, v) \leq 3M - 1 \quad \checkmark$$

" \Leftarrow " We have $\min_u \max_v d(u, v) \leq 3M - 1$

~~If~~ If $u \neq i_A$ for some $1 \leq i \leq h$, then

$$\max_v \text{dist}(u, i'_A) = \infty \text{ for any } i' \neq i$$

$$\Rightarrow \max_v \text{dist}(u, v) = \infty$$

Thus $\min_u \max_v \text{dist}(u, v)$ is minimized by some $u = i_A$

$$\Rightarrow \max_v \text{dist}(i_A, v) \leq 3M - 1$$

$$\text{in particular: } \text{dist}(i_A, i_D) \leq 3M - 1$$

Consider shortest path π from i_A to i_D

First edge cannot be of the form (i_A, v) with weight $3M - 1$ (by rule (3))

because $v \neq i_D$ by construction of H and any other edge

(v, v') will have weight $\geq M$ making π have weight $> 3M - 1$

Thus only path from i_A to i_D must be of the form

$i_A \rightarrow j_B \rightarrow k_C \rightarrow i_D$ for some j and $k \Rightarrow$ neg. triangle i, j, k