

Fast Computation by Population Protocols With A Leader

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Introduction

- ▶ There are a number of different formal models of computation: Turing machines, register machines, lambda calculus etc.
- ▶ Population Protocols are another such model of computation
- ▶ Lots of agents with limited local state and no information about the global state (e.g., molecules in solution, sensors on vehicles etc.)
- ▶ Agents interact randomly without a central authority
- ▶ By carefully tuning the way agents interact, they can be made to compute some useful global property

Contents

- ▶ Population Protocols (in general)
- ▶ Population Protocols (for computation)
- ▶ Building blocks of the Population Protocol computer
- ▶ Operations of the Population Protocol computer
- ▶ Possible optimizations, outlook, applications

Population Protocols

- ▶ Set of agents $\{A_1 \dots A_n\}$, not ordered (numbering used to facilitate description of model)
- ▶ Finite set of states $\{Q_1 \dots Q_k\}$: Each agent is in one of these states at a time
- ▶ Number of states is a property of the protocol, not the input size \Rightarrow The number of states **must not depend on n**
- ▶ Total agent state: Multiset of elements of Q
- ▶ Transition function $(a, b) \mapsto (a', b')$, takes an **ordered** pair of states (can be thought of as initiator and responder) and gives new states for both agents

Population Protocols

- ▶ Interaction: Pick two **distinct** agents (A_i, A_j) of Q , apply the transition function to update their states
- ▶ Execution: infinite sequence of agent pairs (A_i, A_j) , specifying which two agents transition in this interaction
- ▶ Fairness: originally an adversary that guarantees: if some agent configuration occurs infinitely often, then any configuration reachable also occurs infinitely often during the execution
- ▶ but in this paper: focus on random uniform pick of pairs (i, j)
- ▶ Convergence: After a certain number of execution steps, all agents will remain in one of the final states forever
- ▶ Initialization of states: can be uniform (if doing leader election), or based on input (when computing predicates)

Population Protocols by example: Leader election

- ▶ Two states: 1 (leader), 0 (follower)
- ▶ All agents start in state 1
- ▶ Transition: $(1, 1) \mapsto (1, 0)$
- ▶ Example (red: initiator, blue: responder):

[1, 1, 1, 1, 1]

[1, 1, 0, 1, 1]

[1, 1, 0, 1, 1]

[1, 1, 0, 0, 1]

[1, 1, 0, 0, 1]

[1, 0, 0, 0, 1]

[1, 0, 0, 0, 0]

- ▶ This protocol takes an expected n^2 interactions to converge

Computation with Population Protocols

- ▶ Agents $A_1..A_n$
- ▶ Integer registers $R_1..R_m$, each agent stores one bit of each register **in unary**
- ▶ Value of register R_k : $\sum_{i=1}^n A_i[k]$ (remember agents are not ordered)
- ▶ Therefore, for a population size of n , each register can store a number from 0 to n .
- ▶ State of agent: One bit for each register, plus additional information about the current instruction being executed, remember the number of states is **not dependent on n**
- ▶ Designated **leader agent**: Tells other agents which instruction to execute, when to move from one instruction to the next
- ▶ Program: List of instructions that operate on registers (addition, comparison, zero test) plus control flow instructions (conditions, loops)

Building block: Epidemics

- ▶ Simplest building block of Population Protocol algorithms
- ▶ Used to spread a small piece of information (register bit, current instruction)
- ▶ Leader starts epidemics to tell all agents to execute next instruction
- ▶ States: 0 (susceptible), 1 (infected)
- ▶ Initialization: all agents start in 0 state, except for leader
- ▶ Transition: $(1, 0) \mapsto (1, 1)$
- ▶ Convergence (all agents infected) w.h.p. guaranteed in $\mathcal{O}(n \log n)$ interactions

Building block: Phase clock

- ▶ Any instruction needs a certain number of interactions to complete w.h.p. (typically $\Theta(n \log n)$)
- ▶ Leader needs to broadcast signal to start next instruction at the right time
- ▶ Problem: leader has no knowledge of other interactions, finite state
- ▶ Solution: use duration of an epidemic to get a sense of time
- ▶ reduce variance by giving the epidemic m different stages, tunable parameter, larger m means longer clock cycle (m too big does not hurt)
- ▶ States $0 \dots m - 1$, leader starts in state 0, all others in state $m - 1$

Building block: Phase clock

- ▶ Transition:
 - $(a, b) \mapsto (a, b + 1 \pmod m)$ responder is leader, $a = b$
 - $(a, b) \mapsto (a, b)$ responder is leader, $a \neq b$
 - $(a, b) \mapsto (a, a)$ responder is not leader,
 $a \in [b + 1..b + \frac{m}{2}] \pmod m$
 - $(a, b) \mapsto (a, b)$ responder is not leader,
 $a \notin [b + 1..b + \frac{m}{2}] \pmod m$
- ▶ phase: leader receives its own stage, goes to next stage
- ▶ round: leader returns to stage 0 (m phases)
- ▶ For any d_1 and c , there is a parameter m and a constant d_2 so that the phase clock completes n^c rounds each taking between $d_1 \ln n$ and $d_2 \ln n$ interactions with probability at least $1 - n^{-c}$.

Building block: Duplication

- ▶ used to add two registers A, B
- ▶ States: $(0, 0), (0, 1), (1, 1)$ (two register bits)
- ▶ Register state $(1, 0)$ is converted to $(0, 1)$ beforehand
- ▶ Transition: $((1, 1), (0, 0)) \mapsto ((0, 1), (0, 1))$
 $((0, 0), (1, 1)) \mapsto ((0, 1), (0, 1))$
- ▶ 1s from first register are moved to second register
- ▶ invariant: preserves $A + B$ after every step
- ▶ if $A + B \leq n$, eventually all 1s from A will have been moved to B
- ▶ Convergence w.h.p. can take $\Theta(n^2)$ interactions
- ▶ Convergence w.h.p. in $\mathcal{O}(n \log n)$ interactions guaranteed if $2A + B \leq \frac{n}{2}$
- ▶ Test for success: $A = 0$?

Building block: Cancellation

- ▶ used to compare two registers A, B
- ▶ States: $(0, 0), (0, 1), (1, 0)$ (two register bits)
- ▶ Register state $(1, 1)$ is converted to $(0, 0)$ beforehand
- ▶ Transition: $((1, 0), (0, 1)) \mapsto ((0, 0), (0, 0))$
 $((0, 1), (1, 0)) \mapsto ((0, 0), (0, 0))$
- ▶ invariant: preserves $A - B$ after every step
- ▶ if $A > B$, eventually A will have $A - B$ 1s, B will have all 0s
- ▶ if $B > A$, eventually B will have $B - A$ 1s, A will have all 0s
- ▶ if $A = B$, eventually $A = B = 0$
- ▶ Convergence w.h.p. can take $\Theta(n^2)$ interactions
- ▶ After $\mathcal{O}(n \log n)$ interactions, w.h.p. the number of $(0, 1)$ states is at most $\frac{n}{8}$, same for the number of $(1, 0)$ states
- ▶ Test for success: $A = 0 \vee B = 0$?

Building block: Probing

- ▶ Test whether there is any agent that satisfies some predicate (typically: is some register bit 1?)
- ▶ States: 0, 1, 2 (in addition to other information at agent)
- ▶ Initialization: leader in state 1 (if not satisfied), 2 (if satisfied), all other agents in state 0
- ▶ Transition:
 - $(x, y) \mapsto (x, \max(x, y))$ responder not satisfied
 - $(0, y) \mapsto (0, y)$ responder satisfied
 - $(1, y) \mapsto (1, 2)$ responder satisfied
 - $(2, y) \mapsto (2, 2)$ responder satisfied
- ▶ if there is an agent satisfying the predicate, eventually all agents will be (and stay) in state 2
- ▶ otherwise, eventually all agents will be (and stay) in state 1
- ▶ Leader checks its state to get result
- ▶ Convergence w.h.p. in $\mathcal{O}(n \log n)$ interactions

Microcode instructions



| Instruction | Effect on state of agent i |
|------------------|---|
| NOOP | No effect. |
| SET(A) | Set $A_i = 1$. |
| COPY(A, B) | Copy A_i to B_i |
| DUP(A, B) | Run duplication protocol on state (A_i, B_i) . |
| CANCEL(A, B) | Run cancellation protocol on state (A_i, B_i) . |
| PROBE(A) | Run probe protocol with predicate $A_i = 1$. |

- ▶ run all operations for $\Theta(n \log n)$ interactions, the constant needs to be tuned (large enough) of course

High-level operations



| Operation | Effect | Implementation | Notes |
|----------------|----------------------|---|---|
| Constant 0 | $A \leftarrow 0$ | SET($\neg A$) | |
| Constant 1 | $A \leftarrow 1$ | SET($\neg A$) $A_{\text{leader}} \leftarrow 1$ | |
| Assignment | $A \leftarrow B$ | COPY(B, A) | |
| Addition | $A \leftarrow A + B$ | COPY(B, X) DUP(X, A) PROBE(X) | May fail with $X \neq 0$ if $A + B > n/2$. |
| Multiplication | $A \leftarrow kB$ | Use repeated addition. | $k = O(1)$ |
| Zero test | $A \neq 0?$ | PROBE(A) | |

- ▶ These basic operations take a constant number of microcode operations, therefore $O(n \log n)$ interactions

Operation: Comparison

Algorithm 1 Comparison algorithm COMPARE.

```
1:  $A' \leftarrow A$ .
2:  $B' \leftarrow B$ .
3:  $C \leftarrow 1$ .
4:  $r \leftarrow 0$ .
5: while true do
6:   CANCEL( $A', B'$ ). A' - B' preserved
7:   if  $A' = 0$  and  $B' = 0$  then
8:     return  $A = B$ . CANCEL successful
9:   else if  $A' = 0$  then (eliminated one register)
10:    return  $A < B$ .
11:   else if  $B' = 0$  then
12:    return  $A > B$ .
13:   end if
14:    $r \leftarrow 1 - r$ .
15:   if  $r = 0$  then CANCEL failed,
16:      $C \leftarrow C + C$ . however  $A < n / 8, B < n / 8$ 
17:     if addition failed then repeat loop for
18:       return  $A = B$ . 2 log2 n times
19:     end if if still no elimination,  $A = B$ 
20:   end if
21:    $A' \leftarrow A' + A'$ . A' - B' doubled
22:    $B' \leftarrow B' + B'$ .
23: end while
```



▶ Requires $\mathcal{O}(\log(n))$ instructions, returns correct result w.h.p.

Operation: Subtraction



Algorithm 2 Subtraction algorithm SUBTRACT.

```
1:  $A' \leftarrow A.$   
2:  $B' \leftarrow B.$   
3:  $\text{CANCEL}(A', B').$   
4: if  $B' = 0$  then If this fails,  $A < n / 8, B < n / 8$   
5:    $C \leftarrow A.$   
6:   return.  
7: end if  
8:  $C \leftarrow 0.$  build C (difference) using binary search  
9: while  $A' \neq B' + C$  do  
10:   $D \leftarrow 1.$   
11:  while  $A' \geq B' + C + D + D$  do find most significant bit  
still missing in C  
12:     $D \leftarrow D + D.$   
13:  end while  
14:   $C \leftarrow C + D.$  introduce this bit to C  
15: end while
```

► Requires $\mathcal{O}(\log^3(n))$ instructions, returns correct result w.h.p.

Other operations

- ▶ Division
 - ▶ Shift divisor to the left as long as its not larger than dividend ($\log^2 n$ instructions)
 - ▶ Subtract from dividend ($\log^3 n$ instructions)
 - ▶ Repeat for all $\log(n)$ bits of dividend
 - ▶ Also keep track of quotient (shift from 1 to the left, add to total)
 - ▶ $\Theta(\log^4 n)$ instructions
- ▶ Extract individual bits
 - ▶ Extract bit: Divide by 2 until desired bit is least significant ($\log n$ divisions)
 - ▶ Test for even / odd by dividing by 2, multiplying by 2, comparing
 - ▶ Set bit: Test bit, if not already correct: Shift 1 to the left to match up with bit, add / subtract to change bit
 - ▶ $\Theta(\log^5 n)$ instructions

Outlook

- ▶ Optimize subtraction by balanced representation
 - ▶ Balanced representation: Each register consists of a positive and a negative part: $A = A^+ - A^-$
 - ▶ Addition: add positive to positive, negative to negative
 - ▶ Subtraction: add positive to negative, negative to positive
 - ▶ Use cancellation to keep parts from growing too big
 - ▶ Faster subtraction also means faster division
- ▶ Faster simulation of LOGSPACE turing machines
- ▶ Faster evaluation of semilinear predicates using random-walk broadcast
- ▶ Obtain a single leader in $\mathcal{O}(n \log^k n)$ interactions
- ▶ Fault tolerance, non-uniform distribution of interactions