

# Fast Dynamic Distance Computation via Dynamic Spanners

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Habilitation Colloquium

University of Salzburg

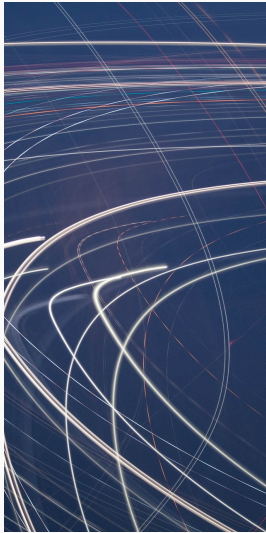
# Big Data

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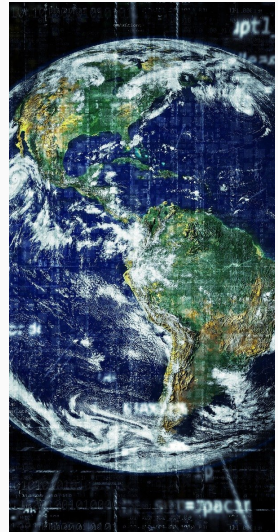
# The three V's



**Volume**

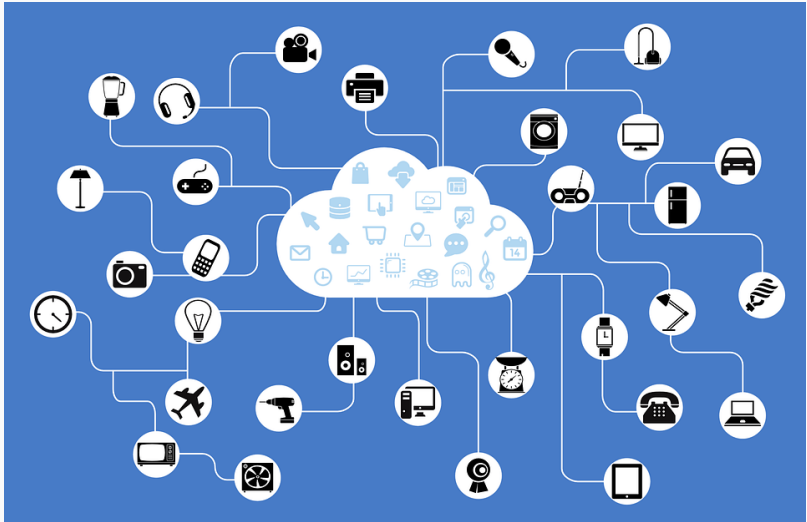


**Velocity**



**Variety**

# Graphs are Everywhere





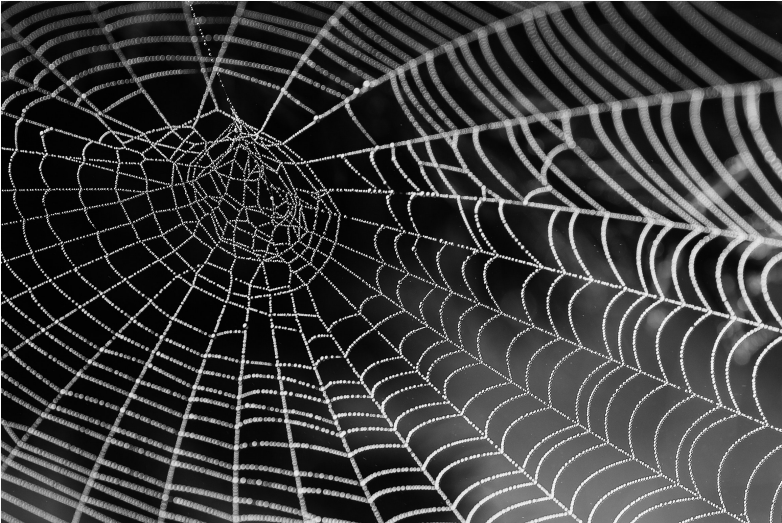
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# Space Reduction

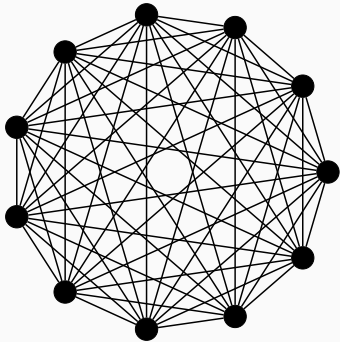
“Sketching”



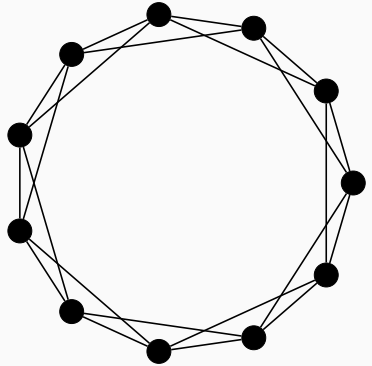
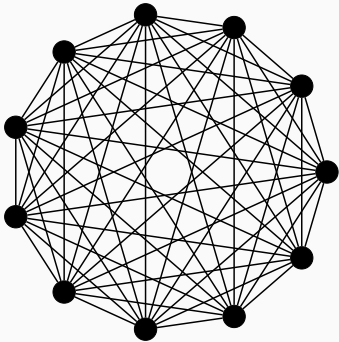
$\approx$



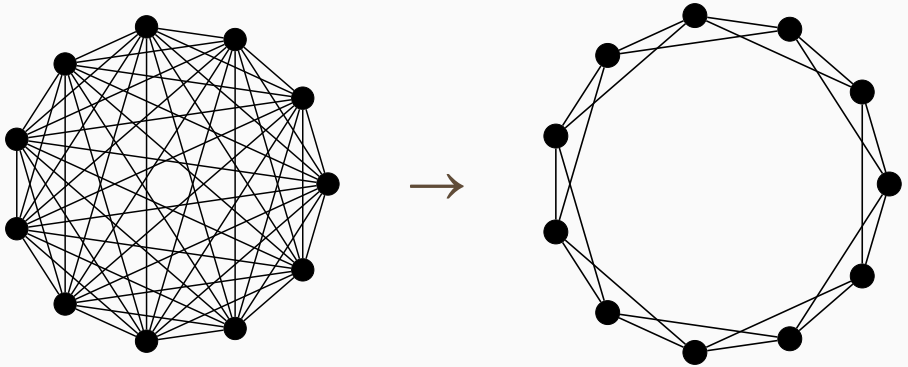
# Graph Sparsification



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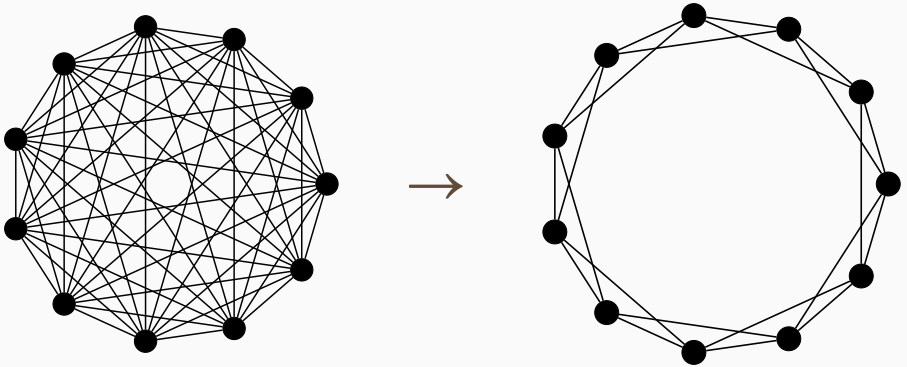


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**Goal:** Reduce number of edges

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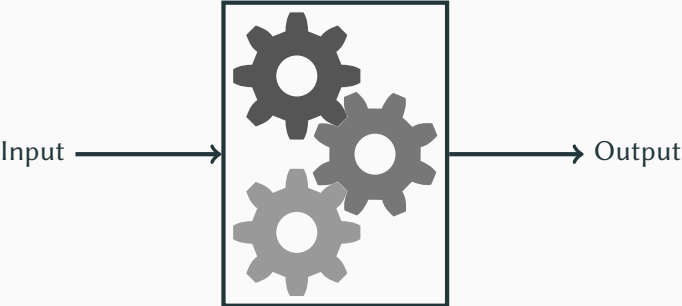
...at cost of approximation



# Dynamic Algorithms

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# Static Approach



# Dynamic Environments

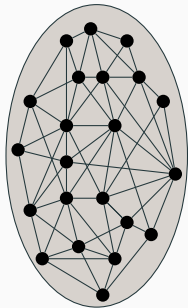


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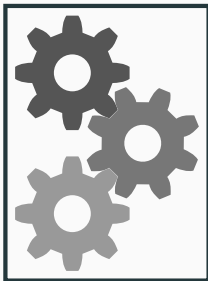
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# Problem Setting

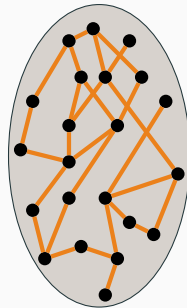
Input graph  $G$



Algorithm

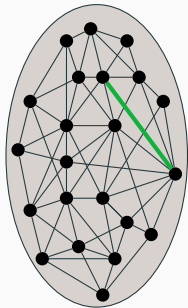


Sparsifier  $H$

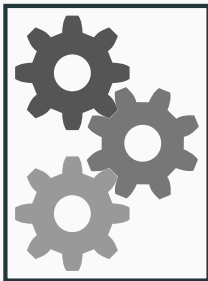


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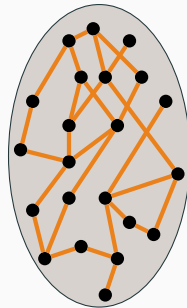
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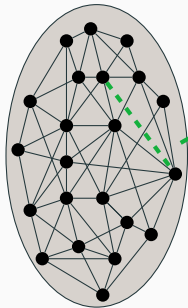
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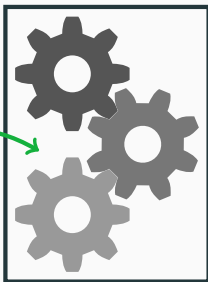
Adversary inserts  
and deletes edges

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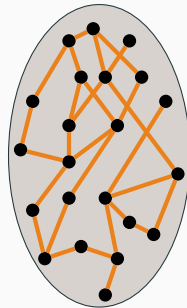
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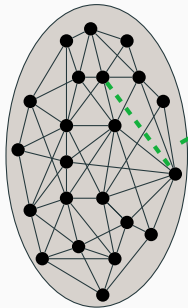
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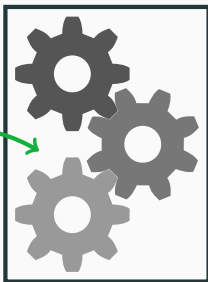
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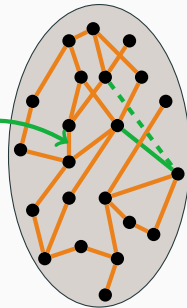


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Sparsifier  $H$



Algorithm adds and  
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## Example 1: Distance-Preserving Sparsification

**Definition** ([Peleg, Schäffer '89])

A **spanner** of **stretch**  $t$  of  $G = (V, E)$  is a subgraph  $H = (V, E')$  such that

$$\text{dist}_G(u, v) \leq \text{dist}_H(u, v) \leq t \cdot \text{dist}_G(u, v)$$

for all pairs of nodes  $u, v \in V$ .

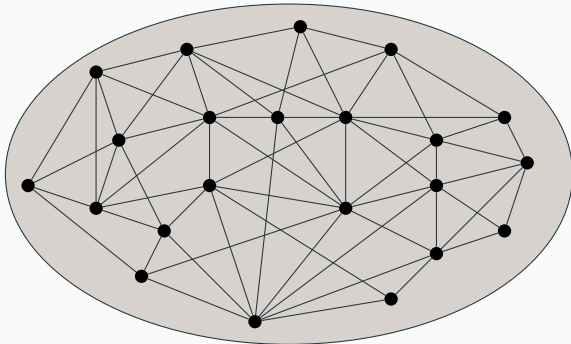
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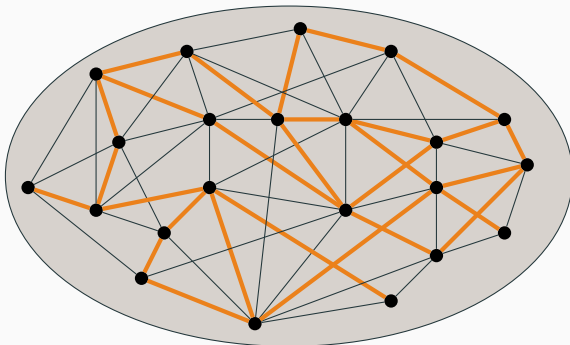
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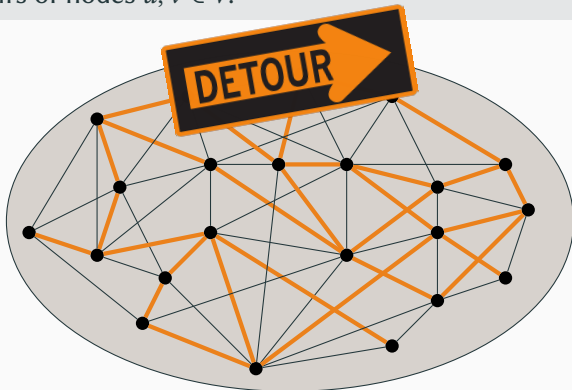
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Distributed SSSP: **boosting** approach for better approximation

[Becker, F, Karrenbauer, Lenzen '17]

# Our Spanner Results

## **Theorem** ([Baswana, Khurana, Sarkar '12])

*For every  $k$ , there is a randomized dynamic algorithm that maintains a spanner of stretch  $t = 2k - 1$*

- with  $O(n^{1+1/k} k^8 \log^2 n)$  and  $O(7^{k/2})$  amortized update time,*
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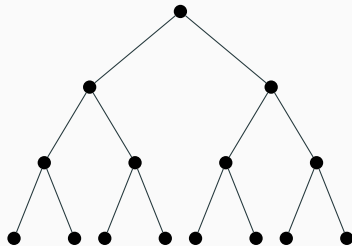
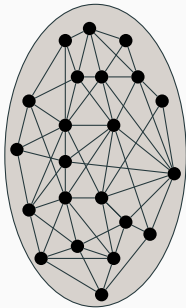
## Theorem ([Bernstein, F, Henzinger '19])

*For every  $k$ , there is a randomized dynamic algorithm that maintains a  $(2k - 1)$ -spanner with  $O(n^{1+1/k} k \log^7 n \log \log n)$  edges and worst-case update time  $O(20^{k/2} \log^3 n)$ .*



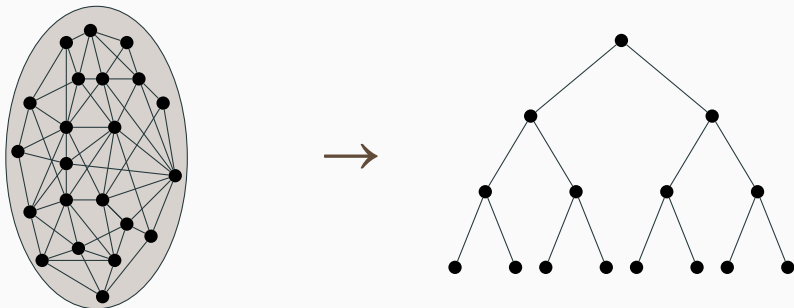
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**Idea:** Embed distance metric into tree metric



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**Results:** First dynamic algorithms for tree embeddings:

- Average stretch [F, Goranci '19]  
(Recent improvement: [Chechik, Zhang '20])
- Expected stretch [F, Goranci, Henzinger '21]

Applications to distance oracles and buy-at-bulk network design

## Example II: Cut-Preserving Sparsification

**Definition** ([Benczúr/Karger '00])

A  $(1 \pm \epsilon)$ -cut sparsifier of  $G$  is a weighted subgraph  $H$  such that, for every cut  $(C, V \setminus C)$ , the edges  $F := E[C, V \setminus C]$  crossing the cut have weight

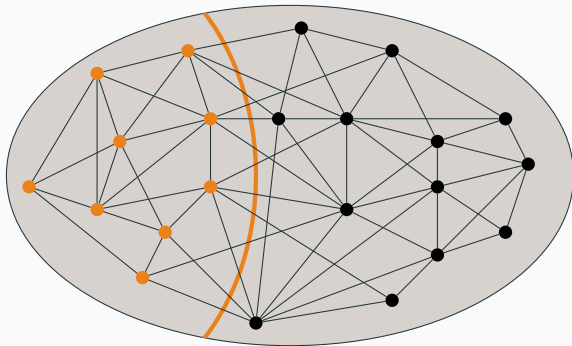
$$(1 - \epsilon) \cdot w_G(F) \leq w_H(F) \leq (1 + \epsilon) \cdot w_G(F)$$

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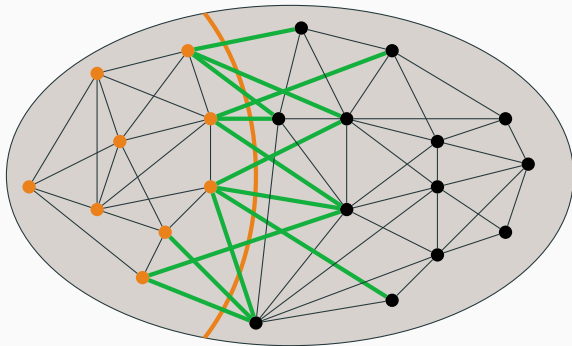


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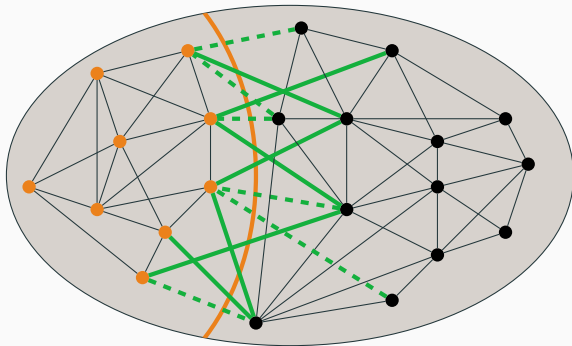


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First dynamic algorithm for this problem

Spectral sparsifier with similar guarantees at cost of amortization

# Dynamic Distance Approximation

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# Towards Assumption-Free Algorithms

## “Gold standard”:

- Fully dynamic
- Worst-case update time
- Deterministic
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## Contribution

We add to this list:  $(1 + \epsilon)$ -approximate distance approximation in unweighted, undirected graphs [van den Brand, F, Nazari '22]

## Our Results

Distance approximation in unweighted, undirected graphs:

Approx	Type	Update Time
$1 + \epsilon$	single pair	$O(n^{1.407} \epsilon^{-2})$
$1 + \epsilon$	single source	$O(n^{1.529} \epsilon^{-2})$
$1 + \epsilon$	$k$ sources	$O(n^{1.529} + kn) \cdot O(\epsilon^{-1}) \sqrt{2 \log_{1/\epsilon} n}$
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**Warm-up:** *Randomized*  $(1 + \epsilon)$ -approximate single-source

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## Related work

Randomized algorithm for maintaining  $(1 + \epsilon, n^{o(1)})$ -spanner of size  $n^{1+o(1)}$  with update time  $O(n^{1.529})$  [Bergamaschi et al. '21]

# Hitting Set

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# Emulator Construction

## Definition

A  $(1 + \epsilon, \beta)$ -**emulator** of  $G = (V, E)$  is a graph  $H = (V, E')$  such that

$$\text{dist}_G(u, v) \leq \text{dist}_H(u, v) \leq (1 + \epsilon) \cdot \text{dist}_G(u, v) + \beta$$

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**Emulator**  $H$  has two types of edges:

- For every light node of degree  $\leq \sqrt{n}$ : edges to all neighbors
- For every node in hitting set: (weighted) edges to all nodes in distance  $\leq \lceil 6/\epsilon \rceil$

similar to [Henzinger, **K**, Nanongkai '13; Dor, Halperin, Zwick '97]

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**Overall:** multiplicative error of  $1 + \frac{\epsilon}{2}$ , additive error of 2

## Theorem ([Sankowski '05])

*Given any  $0 < \delta < 1$  and any sets  $A, B \subseteq V$ , there is a randomized algorithm for maintaining the  $S \times V$  distances up to  $\leq \Delta$  with update time  $\tilde{O}(\Delta(n^{\omega(1,\delta,1)-\delta} + n^{1+\delta} + |A||B|))$ .*



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- If  $d_G(s, v) \leq \lceil 6/\epsilon \rceil$ : distance from algebraic data structure
- If  $d_G(s, v) > \lceil 6/\epsilon \rceil$ , then approximation from  $H$  becomes  $(1 + \frac{\epsilon}{2})d_G(s, v) + 2 \leq (1 + \frac{\epsilon}{2})d_G(s, v) + \frac{\epsilon}{3}d_G(s, v) \leq (1 + \epsilon)d_G(s, v)$

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- Algebraic data structure can be extended to slowly changing set of nodes



## Conclusion

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- Are there “natural” separations?

# Thank you!

