

On Dynamic Graph Algorithms with Predictions

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Dynamic Environments

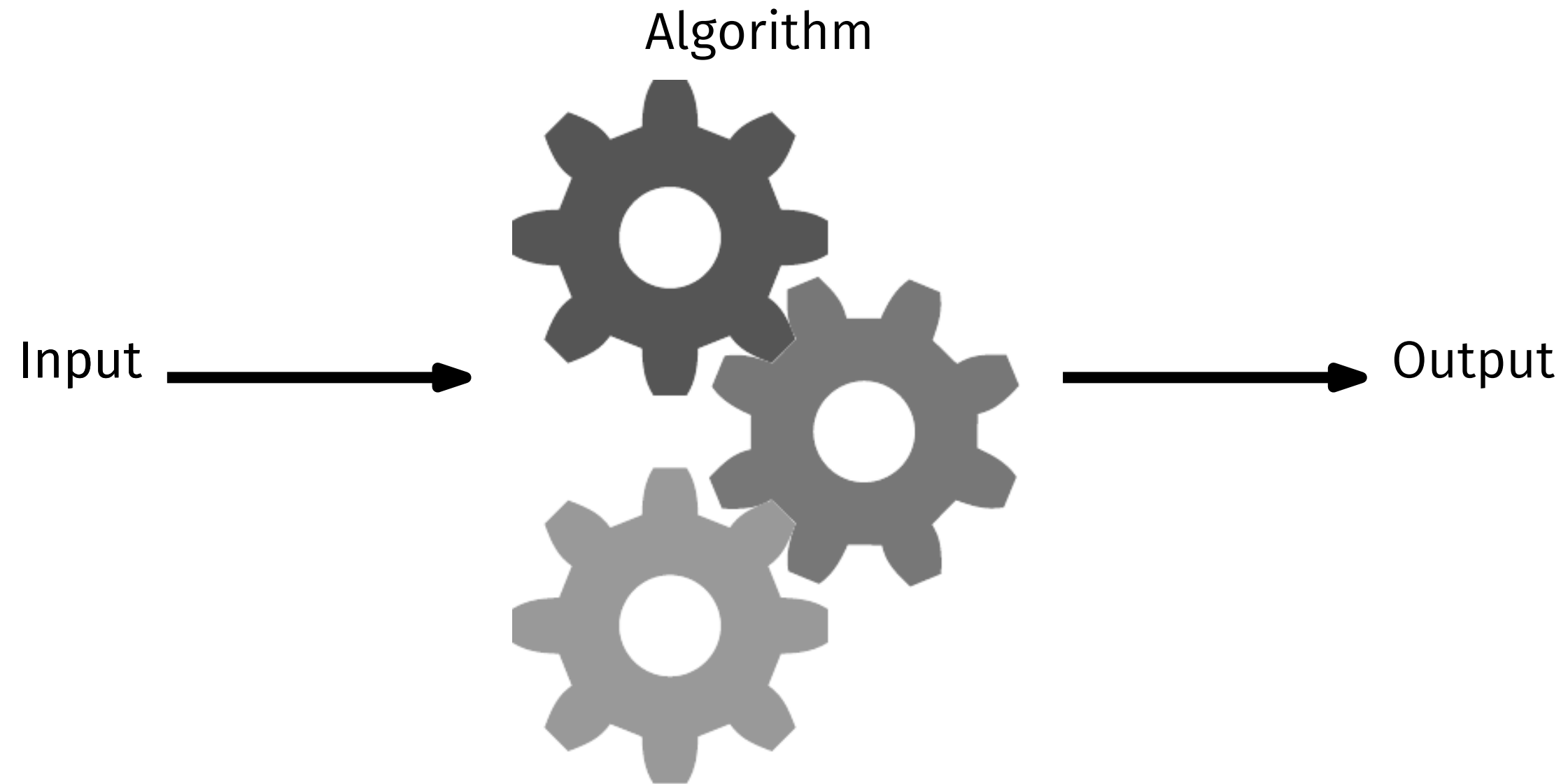


A digital display board showing train schedules. At the top right is a clock and the DB logo. The board lists destinations, platform numbers, and status. A yellow banner at the bottom contains a message about DB train traffic.

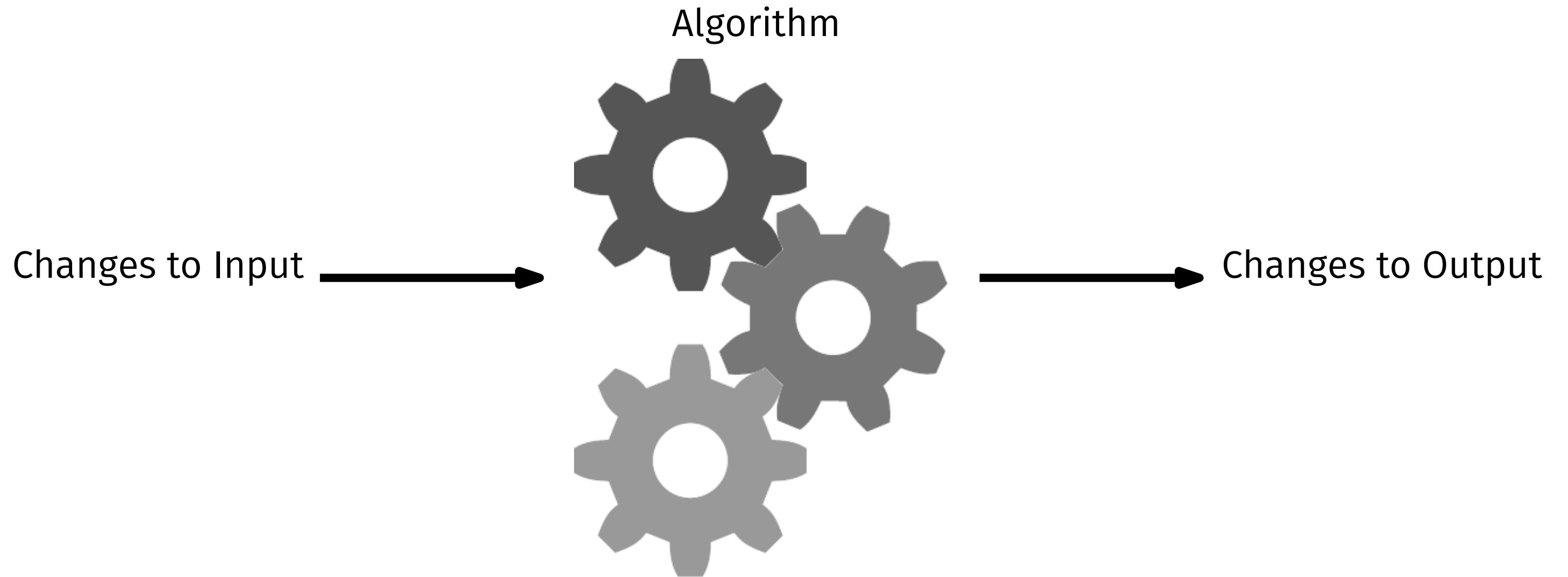
Ziel Destination	Gleis Platform / Voie	
Mannheim-Friedrich	11	
Gernsheim	17	Train is cancelled
Köln Hbf	7	Train is cancelled
Berlin Hbf	9	Train is cancelled
Passau Hbf	6	Train is cancelled
Siegen	16	
Saarbrücken Hbf	20	
Fulda	8	Train is cancelled
Bruxelles-Midi	19	Aujourd'hui du qua
Hanau Hbf	5	ai 5 - Heute auf G

r DB-Zugverkehr beeinträchtigt. Bitte
nd informieren Sie sich auch im Internet

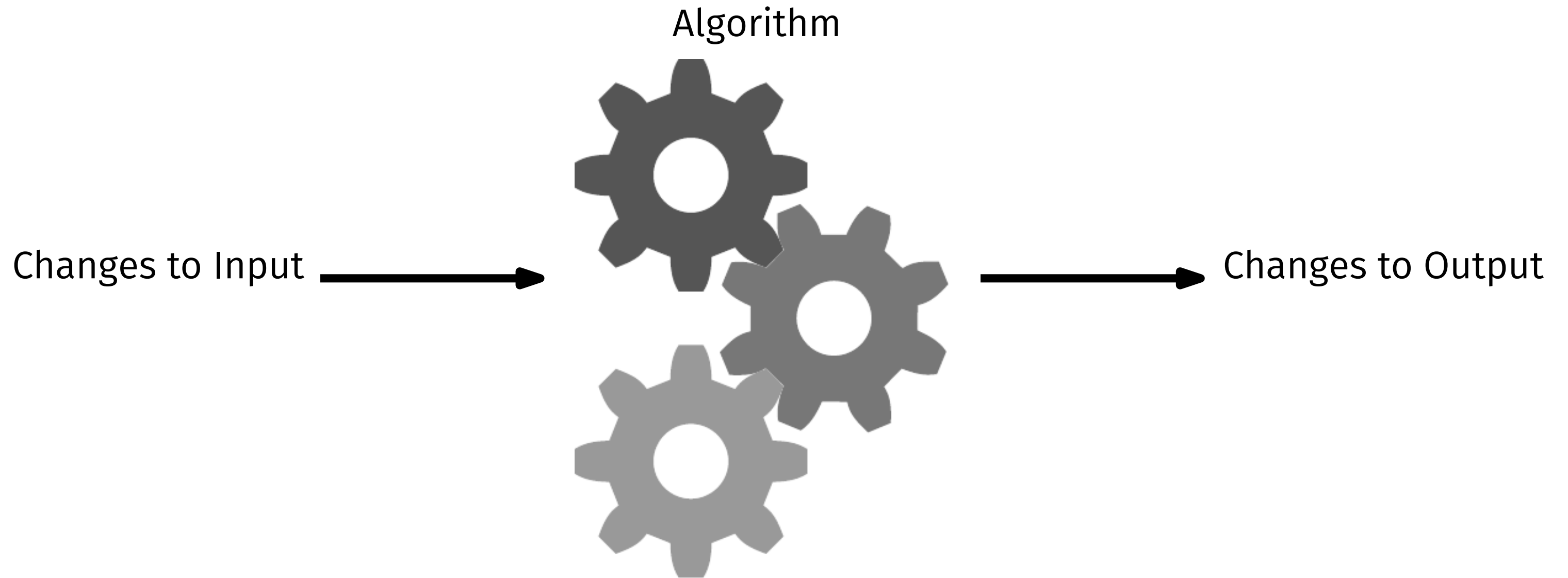
Dynamic Algorithms



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Dynamic Algorithms



Updates

- Insertions (*incremental*) or deletions (*decremental*) of edges/vertices, or both (*fully dynamic*)
- Fast worst-case or amortized update time

Other Models of Evolving Data

Streaming Algorithms

- Focus on space usage
- Standard model: insertions
- Impossibility results for single-pass streaming

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Streaming Algorithms

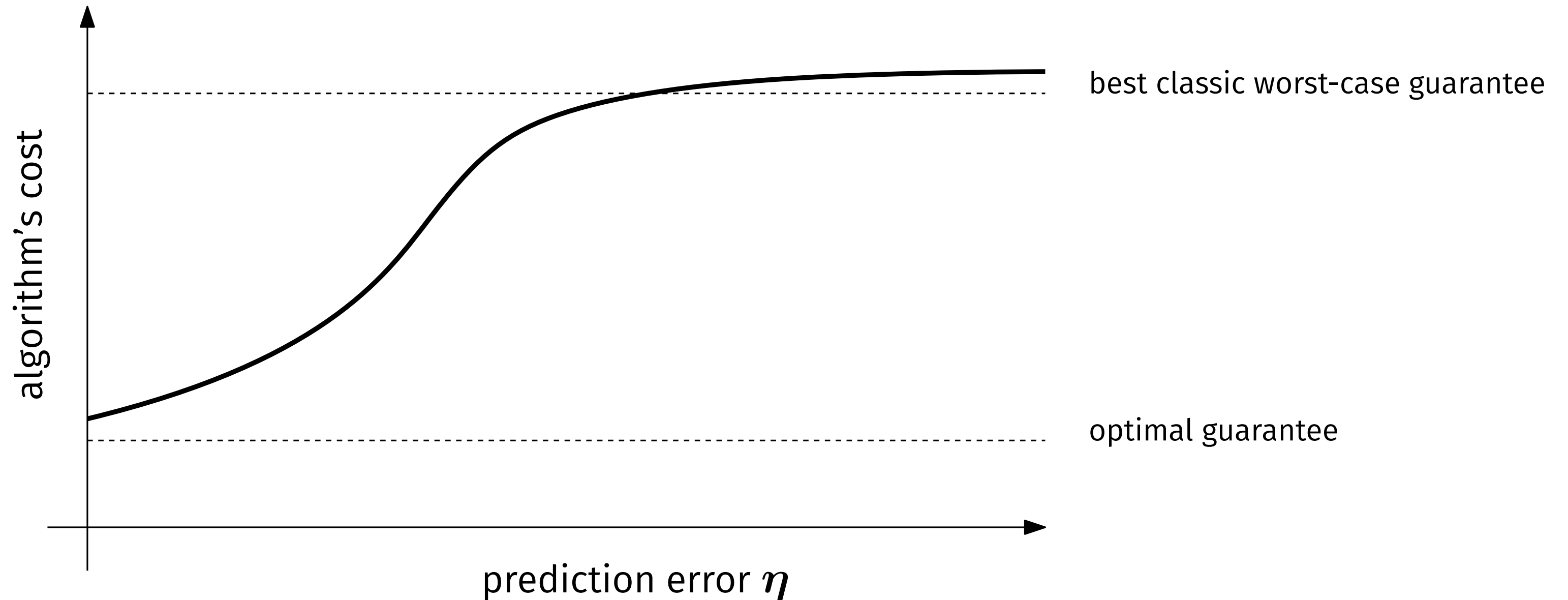
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Online Algorithms

- Focus on competitive ratio of output
- Standard model: irrevocable decisions
- Online algorithms with recourse

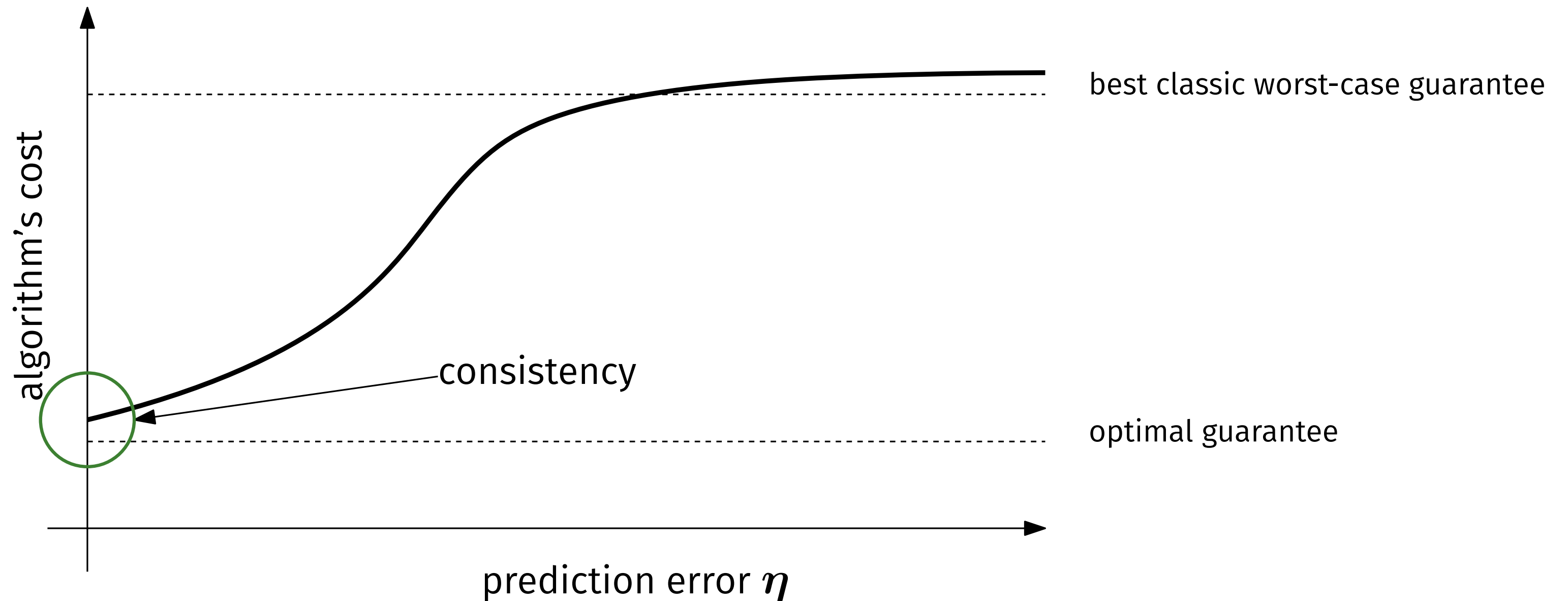
Learning-Augmented Algorithms

Input + black-box **predictions** (possibly inaccurate, with some **error** η)



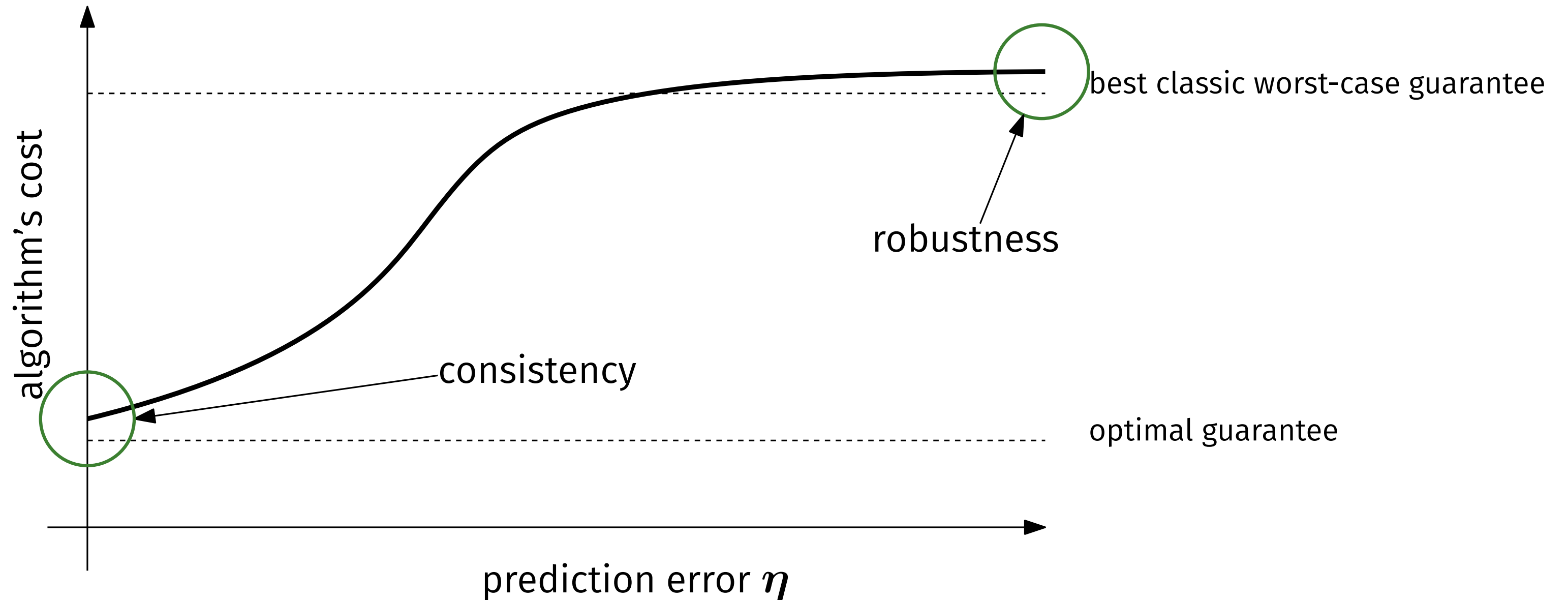
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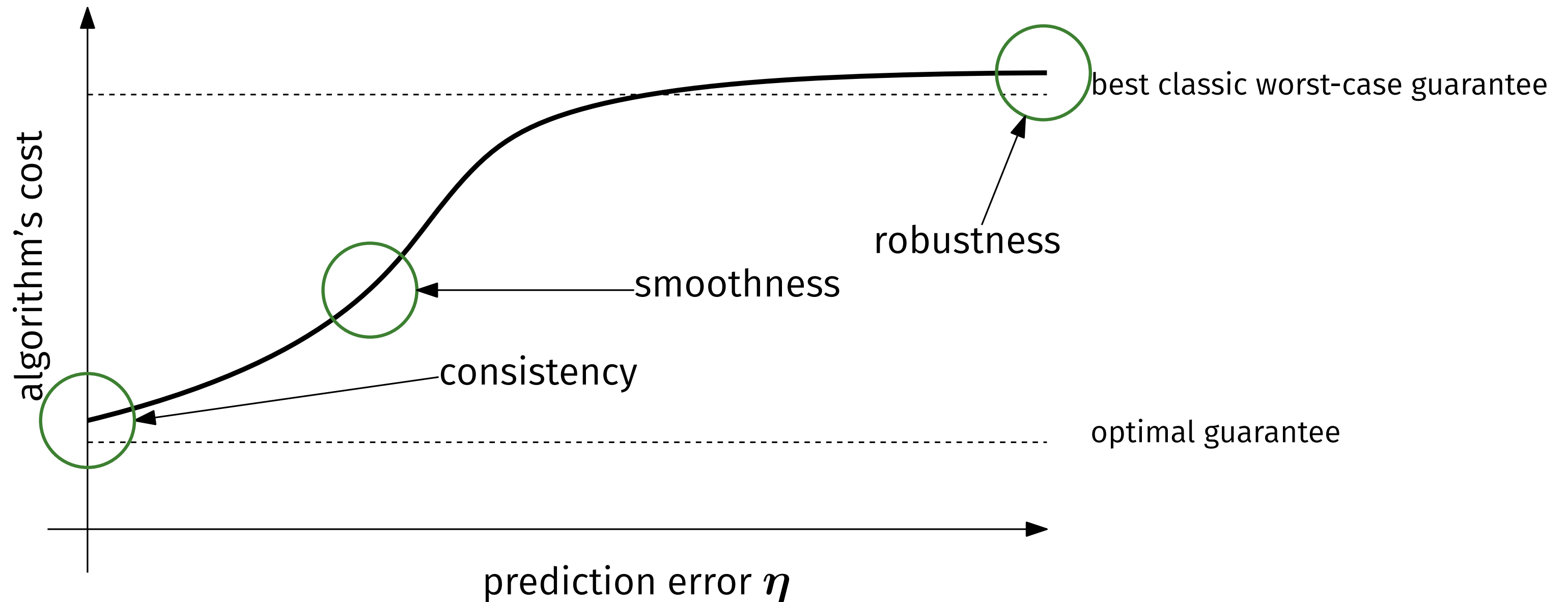
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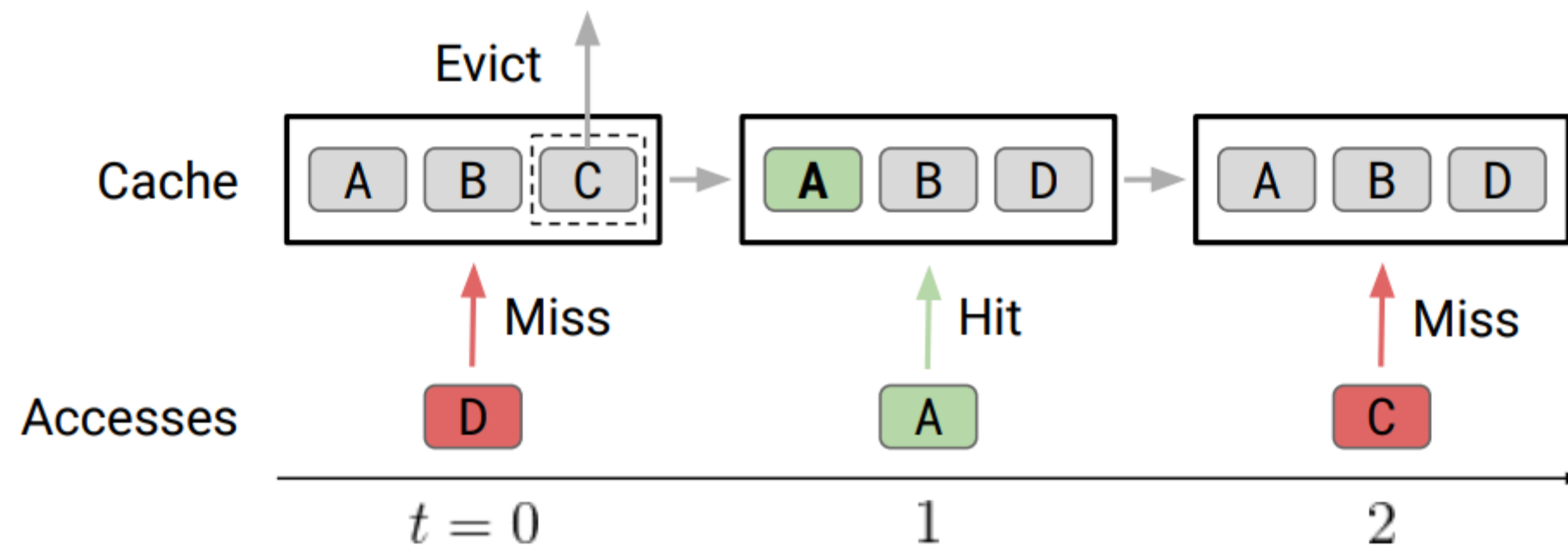


Predictions can improve **competitive ratio** of **online** algorithms

First applications:

Ski-rental and ad allocation,
Caching

[Mahdian, Nazerzadeh, Saberi '07]
[Lykouris, Vassilvitskii, ICML'18]



source: arxiv.org/abs/2006.16239

Possible Predictions:

Number of days skiings,

Frequencies of keywords used,

When will the currently requested item be requested again?

How can predictions improve **dynamic** algorithms?

- Predict **future** updates
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- With predictions we can do what is (provably) impossible without them
- (Provable) Gap between offline and online problem

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What is provably impossible? → Conditional lower bounds

Discussion of Conditional Lower Bounds

[Abboud, Vassilevska Williams '14]

Influential paper presenting conditional lower bounds for dynamic problems based on static hardness assumptions:

- Strong Exponential Time Hypothesis
- No truly subquadratic 3SUM
- No truly subcubic all-pairs shortest paths
- No almost linear time triangle detection
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“Problem”: These reductions also apply to the *offline* dynamic model

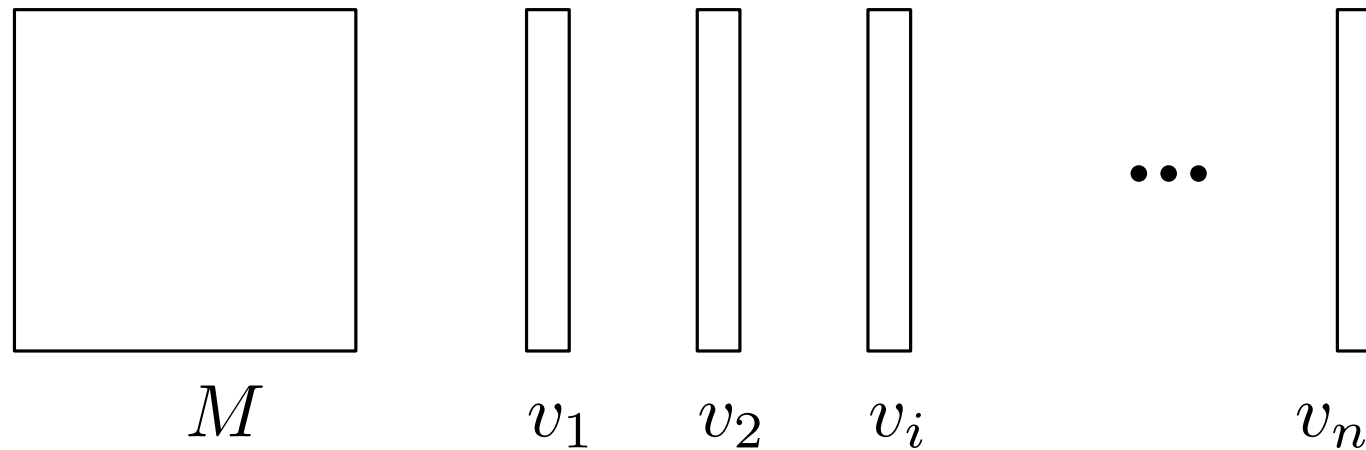
Online Matrix-Vector Multiplication Hypothesis [Henzinger, K, Nanongkai, Saranurak '15]

Input:

- M — Boolean $n \times n$ matrix, given **offline**
- v_1, \dots, v_n — Boolean $n \times 1$ vectors, given one by one **online**

Output: Mv_1, Mv_2, \dots, Mv_n

Hypothesis: requires $n^{3-o(1)}$ time



Does **not hold offline** — compute $M \cdot [v_1, \dots, v_n]$ in $O(n^\omega)$ time

Online Matrix-Vector Multiplication **with Predictions**

[this work]

Input:

- M — Boolean $n \times n$ matrix , given **offline**
- $\hat{v}_1, \dots, \hat{v}_n$ — **predicted** vectors, given **offline**
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Algorithm:

- Preprocessing in $O(n^\omega)$ time

$$M \cdot [\hat{v}_1, \dots, \hat{v}_n]$$

- Each request in $O(n\eta_i)$ time, $\eta_i = \|v_i - \hat{v}_i\|_1 = \|v_i - \hat{v}_i\|_0$

$$Mv_i = M(v_i - \hat{v}_i + \hat{v}_i) = M(v_i - \hat{v}_i) + M\hat{v}_i$$

$$\begin{array}{cc} \uparrow & \uparrow \\ O(n\eta_i) & O(n) \end{array}$$

Total time: $O(n^\omega + n\eta)$, $\eta = \sum_{i=1}^n \eta_i$

Incremental All-Pairs Reachability

Update: Insert directed edge (u, v)

Query: Is there a path from a to b ?

Upper bound: $O(nm)$ total update time (for n nodes and m edges) [Italiano, TCS 86]

Lower bound: n^2 updates and n^2 queries require $n^{3-o(1)}$ time, under OMv

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Offline = all-pairs **bottleneck** paths [this work]

$(O(n^{(3+\omega)/2}) \leq O(n^{2.687})$ **pre-processing** time, via min-max matrix product [DPO9])

$$D[a, b] = \min_{P \in \{\text{paths from } a \text{ to } b\}} \max_{e \in P} \text{weight}(e)$$

Edge weights = arrival time

If $D[a, b] \leq j \implies$ after j insertions: path from a to b

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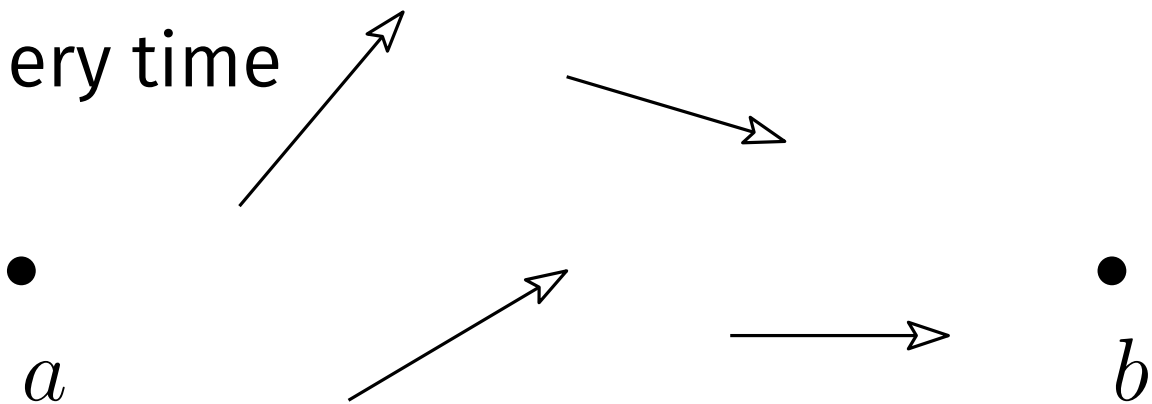
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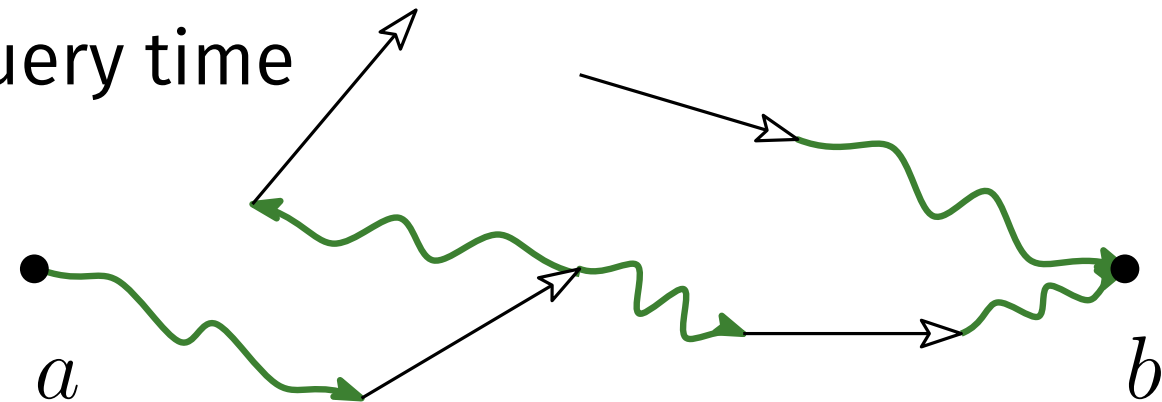
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Our results for graph problems

Partially dynamic

(edge insertions **or** deletions)

Prediction: **update sequence**

- Transitive closure
- Aproximate APSP

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- Exact matching
- Single-source reachability
- many more...

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ℓ_1 error per operation \rightarrow

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 see also [Liu, Srinivas '24]

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 see also [Henzinger, Saha, Seybold, Ye, '24]

Discussion and Future Directions

- More problems with faster offline algorithms?
(see [McCauley et al. ICALP '25], [Górkiewicz, Karczmarz ICALP '25])
- Insisting on offline-online gap might be too restrictive
More fine-grained or practical models for algorithms with predictions?

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Thank you!